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ABSTRACT The rowmotion action on order ideals or on antichains of a finite partially ordered set has been studied (under a variety of names) by many authors. Depending on the poset, one finds unexpectedly interesting orbit structures, instances of (small order) periodicity, cyclic sieving, and homomesy. Many of these nice features still hold when the action is extended to $[0, 1]$ -labelings of the poset or (via detropicalization) to labelings by rational functions (the *birational* setting).

In this work, we parallel the birational lifting already done for order-ideal rowmotion to antichain rowmotion. We give explicit equivariant bijections between the birational toggle groups and between their respective liftings. We further extend all of these notions to labellings by *noncommutative* rational functions, setting an unpublished periodicity conjecture of Grinberg in a broader context.

1. INTRODUCTION

Combinatorial rowmotion is a well-studied action on the set of order ideals $\mathcal{J}(P)$ or on the set of antichains $\mathcal{A}(P)$ of a finite poset P . It was first studied as a map on $\mathcal{A}(P)$ by Brouwer and Schrijver [2], and goes by several names. In recent literature, the name “rowmotion,” due to Striker and Williams [27] (who summarize the history), has stuck. An updated historical survey is available in Thomas and Williams [28, § 7].

Rowmotion has proven to be of great interest in dynamical algebraic combinatorics. On several “nice” posets (e.g. positive root posets or minuscule posets, such as products of two chains), rowmotion exhibits various phenomena including *periodicity* (of a relatively small order), *cyclic sieving* (as defined by Reiner, Stanton, and White [20]), *homomesy* (where a natural statistic, e.g. cardinality, has the same average over every orbit) [1, 10, 13, 18, 19, 22, 30, 29], and *resonance* (see [4, 5]). Rowmotion is related to Auslander–Reiten translation on certain quivers [32].

Quite surprisingly, some of these features extend to the piecewise-linear (order polytope) level and can be lifted further to the birational level [6]. One sometimes gets periodicity of the same order as the combinatorial map, and often homomesy extends as well [8, 9, 16]. Just as one example, the file-cardinality homomesy for order-ideal rowmotion on rectangular posets [19, Thm. 19ff] lifts to a birational homomesy [16, Thm. 2.16]; Rush and Wang’s extension of this result to all minuscule posets [22, Thm. 1.2] has recently been lifted to the birational realm by S. Okada [17].

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It is a continuing mystery why certain properties of combinatorial rowmotion on many families of posets lift to the birational realm. This question is still far from answered, but Hopkins has shown some properties must lift to the birational realm on posets which satisfy the tCDE property and have a grid-like structure [11]. Birational rowmotion is related to Y -systems of type $A_m \times A_n$ described in Zamolodchikov periodicity [21, § 4.4].

The lifting of order-ideal rowmotion (herein denoted $\rho_{\mathcal{J}}$) to BOR-motion (birational order rowmotion) proceeds by first writing $\rho_{\mathcal{J}}$ as a product of involutions called *toggles*, each of which acts on $\mathcal{J}(P)$, the set of order ideals of a poset. These toggles are then extended to Stanley’s *order polytope* $\mathcal{OP}(P)$, and then lifted further to toggles at the birational level [6], following the lead of Kirillov and Berenstein [15]. Letting \mathbb{K} be a field of characteristic zero, we lift from a piecewise-linear map to a birational map through detropicalization of operations. Any equality of rational expressions (such as periodicity or homomesy) that does not contain subtraction or additive inverses also holds in the piecewise-linear realm (by tropicalization) and furthermore in the combinatorial realm (by restriction); see [9, Remark 10].

As part of a broader study of toggling in general, Striker defined *antichain toggles* that act on $\mathcal{A}(P)$ [26]. The first author gave an explicit isomorphism between these two different toggle groups (on $\mathcal{J}(P)$ and on $\mathcal{A}(P)$) for the same poset P , and extended these results to the piecewise-linear level [12], where $\mathcal{A}(P)$ extends to Stanley’s *chain polytope* $\mathcal{C}(P)$ [23]. These toggles can be used to define the *antichain rowmotion* of [2] and its extension to all of $\mathcal{C}(P)$.

Our goal in this work is to study the parallel lifting of this map on $\mathcal{C}(P)$ to the birational level, which we call *Birational Antichain Rowmotion* or *BAR-motion* (Definition 3.4) for short. We construct equivariant bijections between this action and the previously studied BOR-motion, allowing us to deduce properties of one from the other. We also describe a noncommutative analogue of both these maps (the first originally discovered by Darij Grinberg, unpublished), and prove that these bijections extend even to this realm.

The paper is organized as follows. In Section 2, we include the necessary background on rowmotion at the combinatorial, piecewise-linear, and birational levels, including ways to view them as compositions of transfer maps and as products of toggles. This positions us in Section 3 to define *birational antichain toggling* and *BAR-motion* and construct the explicit bijection between the two different toggle groups at the birational level.

Section 4 contains our results that pertain specifically to graded posets, which are the only ones known thus far to exhibit homomesy or periodicity in the birational realm. Since toggles within the same rank commute with each other, we can toggle them “all at once”. Toggling by ranks (hence the term “rowmotion”) from top to bottom gives one map, but we can also toggle first all even ranks, then all odd ones, giving a map called *gyration* by Striker [25]. Grinberg and the second author worked with graded rescalings of poset labelings in several proofs in [8, 9]. We discuss the analogues of these ideas under the antichain perspective.

In Section 5, we lift our birational actions further to the *noncommutative realm*, where we do not assume commutativity of multiplication. This setting has not appeared in the literature before, but is based on unpublished definitions and conjectures of Darij Grinberg. In this paper, we show that *NOR-motion* (*Noncommutative Order Rowmotion*) and *NAR-motion* (*Noncommutative Antichain Rowmotion*) always exhibit the same order on any given finite poset. We use “noncommutative realm” as a short term, but we really mean “not-necessarily-commutative birational realm” as fields are skew fields.

We defer the proofs of several results in Section 3 since they follow from their noncommutative analogues in Section 5. (We originally proved the results in this realm before realizing we could extend them to the noncommutative setting.) Toggles are no longer involutions, so it is surprising that many other key properties do continue to hold (with suitably modified definitions), such as the isomorphism between the order and antichain toggle groups.

To summarize, we have four realms (combinatorial, piecewise-linear, birational, and noncommutative) and two rowmotion maps (order-ideal and antichain). Our new work here involves lifting the latter map to the birational and noncommutative realms, and giving explicit equivariant isomorphisms connecting these two maps at the two highest levels. Beyond the inherent interest of showing that Stanley’s transfer maps between $\mathcal{O}(P)$ and $\mathcal{C}(P)$ lift nicely to the birational and noncommutative birational settings, we hope that having different approaches to these maps will help shed light on some of their tantalizing properties. In particular, on several minuscule and root posets, BOR-motion has the same order as combinatorial order-ideal rowmotion, and this is conjectured to extend to NOR-motion as well. Our results show that a proof for NAR-motion would automatically imply it for NOR-motion as well.

To prove refined versions of homomesy in the product of two chain posets, J. Propp and the second author used an equivariant bijection discovered (less formally) by R. Stanley and H. Thomas [19, § 7]. In a separate paper [14] we explore the lifting of this “Stanley–Thomas word” to the piecewise-linear, birational, and noncommutative realms. Although the map is no longer a bijection, so cannot be used to prove periodicity directly, it still gives enough information to prove the homomesy at the piecewise-linear and birational levels (a result previously shown by D. Grinberg, S. Hopkins, and S. Okada). Even at the noncommutative level, the Stanley–Thomas word of a poset labeling rotates cyclically with the lifting of antichain rowmotion.

2. ROWMOTION IN THE COMBINATORIAL, PIECEWISE-LINEAR, AND BIRATIONAL REALMS

This section contains the necessary background for this paper. We discuss the toggle group of a poset P , rowmotion on order ideals and on antichains, and define their generalizations to the piecewise-linear realm. We also discuss the lifting of order-ideal rowmotion to the birational realm. Our new results begin in Section 3 with the birational lifting of antichain rowmotion.

2.1. ROWMOTION IN THE COMBINATORIAL REALM. We assume familiarity with basic notions from the theory of posets, as discussed in [24, Ch. 3]. Throughout this paper P will denote a finite poset.

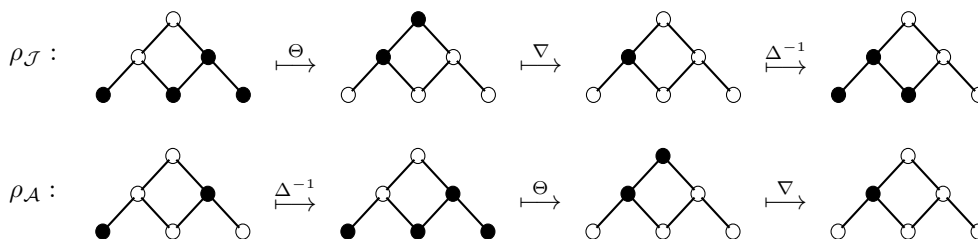
Following the notation of Einstein–Propp [6], we can define rowmotion via the following natural bijections between the set $\mathcal{J}(P)$ of all *order ideals* of P , the set $\mathcal{F}(P)$ of all *order filters* of P , and the set $\mathcal{A}(P)$ of all *antichains* of P .

- The map $\Theta : 2^P \rightarrow 2^P$ where $\Theta(S) = P \setminus S$ is the complement of S (so Θ sends order ideals to order filters and vice versa).
- The *up-transfer* $\Delta : \mathcal{J}(P) \rightarrow \mathcal{A}(P)$, where $\Delta(I)$ is the set of maximal elements of I . For an antichain $A \in \mathcal{A}(P)$, $\Delta^{-1}(A) = \{x \in P : x \leq y \text{ for some } y \in A\}$ (“downward saturation”).
- The *down-transfer* $\nabla : \mathcal{F}(P) \rightarrow \mathcal{A}(P)$, where $\nabla(F)$ is the set of minimal elements of F . For an antichain $A \in \mathcal{A}(P)$, $\nabla^{-1}(A) = \{x \in P : x \geq y \text{ for some } y \in A\}$ (“upward saturation”).

DEFINITION 2.1. Order-ideal rowmotion is the map $\rho_{\mathcal{J}} : \mathcal{J}(P) \rightarrow \mathcal{J}(P)$ given by the composition $\rho_{\mathcal{J}} = \Delta^{-1} \circ \nabla \circ \Theta$. Antichain rowmotion is the map $\rho_{\mathcal{A}} : \mathcal{A}(P) \rightarrow \mathcal{A}(P)$

given by the composition $\rho_{\mathcal{A}} = \nabla \circ \Theta \circ \Delta^{-1}$. Order-filter rowmotion is the map $\rho_{\mathcal{F}} : \mathcal{F}(P) \rightarrow \mathcal{F}(P)$ given by the composition $\rho_{\mathcal{F}} = \Theta \circ \Delta^{-1} \circ \nabla$.

EXAMPLE 2.2. Below we show examples of $\rho_{\mathcal{J}}$ and $\rho_{\mathcal{A}}$ on the positive root poset $\Phi^+(A_3)$. In each step, the elements of the subset of the poset are given by the filled-in circles.



2.2. THE ORDER-IDEAL TOGGLE GROUP. The map $\rho_{\mathcal{J}}$ can also be written as a composition of involutions on $\mathcal{J}(P)$ called *toggles*, as first shown by Cameron and Fon-der-Flaass [3].

DEFINITION 2.3 ([3]). For $v \in P$, the order-ideal toggle corresponding to v is the map $T_v : \mathcal{J}(P) \rightarrow \mathcal{J}(P)$ defined by

$$T_v(I) = \begin{cases} I \cup \{v\} & \text{if } v \notin I \text{ and } I \cup \{v\} \in \mathcal{J}(P), \\ I \setminus \{v\} & \text{if } v \in I \text{ and } I \setminus \{v\} \in \mathcal{J}(P), \\ I & \text{otherwise.} \end{cases}$$

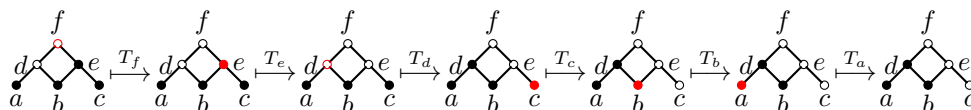
Let $\text{Tog}_{\mathcal{J}}(P)$ denote the toggle group of $\mathcal{J}(P)$, i.e. the subgroup of $\mathfrak{S}_{\mathcal{J}(P)}$ (the symmetric group on $\mathcal{J}(P)$) generated by the toggles $\{T_v : v \in P\}$.

The toggle T_v either adds or removes v from the order ideal if the resulting set is still an order ideal, and otherwise does nothing.

DEFINITION 2.4 ([24, § 3.5]). A sequence (x_1, x_2, \dots, x_n) containing all of the elements of a finite poset P exactly once is called a linear extension of P if it is order-preserving, that is, whenever $x_i < x_j$ in P then $i < j$.

PROPOSITION 2.5 ([3]). For any linear extension (x_1, x_2, \dots, x_n) of P , order-ideal rowmotion is given by $\rho_{\mathcal{J}} = T_{x_1} T_{x_2} \cdots T_{x_n}$.

EXAMPLE 2.6. For the poset $P = [2] \times [3]$ of Example 2.2, as labeled below, (a, b, c, d, e, f) gives a linear extension. We show the effect of applying $T_a T_b T_c T_d T_e T_f$ to the order ideal considered in Example 2.2. In each step, we indicate the element whose toggle we apply next in red. Notice that the outcome is the same order ideal we obtained by the three step process in Example 2.2, demonstrating Proposition 2.5.



2.3. THE ANTICHAIN TOGGLE GROUP. Toggling makes sense in a broader context, as formalized by Striker [26]. We can define *antichain toggles* on $\mathcal{A}(P)$, by replacing $\mathcal{J}(P)$ with $\mathcal{A}(P)$ in the definition. Removing any element from an antichain always yields an antichain, giving a simpler second case.

DEFINITION 2.7 ([26]). Let $v \in P$. Then the antichain toggle corresponding to v is the map $\tau_v : \mathcal{A}(P) \rightarrow \mathcal{A}(P)$ defined by

$$\tau_v(A) = \begin{cases} A \cup \{v\} & \text{if } v \notin A \text{ and } A \cup \{v\} \in \mathcal{A}(P), \\ A \setminus \{v\} & \text{if } v \in A, \\ A & \text{otherwise.} \end{cases}$$

Let $\text{Tog}_{\mathcal{A}}(P)$ denote the toggle group of $\mathcal{A}(P)$, i.e. the subgroup of $\mathfrak{S}_{\mathcal{A}(P)}$ (the symmetric group on $\mathcal{A}(P)$) generated by the toggles $\{\tau_v : v \in P\}$.

The first author constructed an explicit isomorphism between the toggle groups $\text{Tog}_{\mathcal{J}}(P)$ and $\text{Tog}_{\mathcal{A}}(P)$ [12]. A consequence of this isomorphism is that antichain rowmotion is also a product of antichain toggles in an order specified by a linear extension, but starting at the bottom and moving upwards.

PROPOSITION 2.8 ([12, Prop. 2.24]). For any linear extension (x_1, x_2, \dots, x_n) of P , antichain rowmotion is given by $\rho_{\mathcal{A}} = \tau_{x_n} \cdots \tau_{x_2} \tau_{x_1}$.

EXAMPLE 2.9. For the poset $P = [2] \times [3]$, (a, b, c, d, e, f) gives a linear extension. We show the effect of applying $\tau_f \tau_e \tau_d \tau_c \tau_b \tau_a$ to the order ideal considered in Example 2.2. In each step, we indicate the element whose toggle we apply next in red. Notice that the outcome is the same order ideal we obtained by the three step process in Example 2.2, demonstrating Proposition 2.8.



2.4. PIECEWISE-LINEAR DYNAMICS. Now we generalize our actions from subsets of P (i.e. $\{0, 1\}$ -labelings of P) to \mathbb{R} -labelings of the elements of P ; let $\mathbb{R}^P := \{f : P \rightarrow \mathbb{R}\}$ denote the set of such labelings. The toggling perspective allows us to extend these maps from the combinatorial realm (on finite sets) to the piecewise-linear realm (polytopes whose vertices correspond to these sets), and then lift to the birational realm by detropicalizing the operations [6]. The study of piecewise-linear dynamics begins with two polytopes introduced by Stanley [23], the *order polytope* and the *chain polytope* of P . The vertices of these polytopes are the sets $\mathcal{F}(P)$ of order filters and $\mathcal{A}(P)$ of antichains (associating a subset of P with its indicator function labeling). Einstein and Propp defined piecewise-linear toggle operations on the order polytope that match the order-ideal toggle T_v when restricted to the vertices (though here we use order *filters* instead of order ideals) [6, § 3.4].

DEFINITION 2.10 ([23]). Within \mathbb{R}^P the order polytope of P is the set $\mathcal{OP}(P)$ of labelings $f : P \rightarrow [0, 1]$ that are order-preserving (i.e. if $a \leq b$ in P , then $f(a) \leq f(b)$). The chain polytope of P is the set $\mathcal{C}(P)$ of labelings $f : P \rightarrow [0, 1]$ such that the sum of the labels across every chain is at most 1.

By associating a subset of P with its indicator functions, the sets $\mathcal{F}(P)$ and $\mathcal{A}(P)$ describe the vertices of $\mathcal{OP}(P)$ and $\mathcal{C}(P)$ respectively [23]. Similarly, we can define an *order-reversing polytope* $\mathcal{OR}(P)$ to consist of all labelings $f : P \rightarrow [0, 1]$ that are order-reversing (i.e. if $a \leq b$ in P , then $f(a) \geq f(b)$). The vertices of $\mathcal{OR}(P)$ are the order ideals of P . To define toggles, there is no important difference in defining them over $\mathcal{OR}(P)$ as opposed to $\mathcal{OP}(P)$. The piecewise-linear order toggles are typically defined on $\mathcal{OP}(P)$.

DEFINITION 2.11 ([6]). Given a finite poset P , let \widehat{P} denote the poset P with the addition of two elements, $\widehat{0}$ and $\widehat{1}$, satisfying $\widehat{0} < v$ and $\widehat{1} > v$ for all $v \in P$. Let $v \in P$ and $f \in \mathcal{OP}(P)$. The piecewise-linear order toggle $T_v : \mathcal{OP}(P) \rightarrow \mathcal{OP}(P)$ is

$$(T_v(f))(x) = \begin{cases} f(x) & \text{if } x \neq v \\ \max_{y < v} f(y) + \min_{y > v} f(y) - f(v) & \text{if } x = v \end{cases}$$

where we set $f(\widehat{0}) = 0$ and $f(\widehat{1}) = 1$. We use the notation $x < y$ to mean “ y covers x ” and $x > y$ to mean “ x covers y ”. By using cover relations in \widehat{P} we ensure that every element of P covers some element of \widehat{P} and is covered by an element of \widehat{P} . The effect of this involution at $x = v$ is to replace the label at v with the value obtained by reflecting the allowable \mathbb{R} -interval $\left[\max_{y < v} f(y), \min_{y > v} f(y) \right]$ through its midpoint.

The first author defined the following generalization of antichain toggles to the chain polytope $\mathcal{C}(P)$ [12, § 3], which matches our earlier definition of τ_v when restricted to the vertices $\mathcal{A}(P)$.

DEFINITION 2.12 ([12]). For $v \in P$, let $\text{MC}_v(P)$ denote the set of all maximal chains of P through v . The piecewise-linear antichain toggle (or chain polytope toggle) $\tau_v : \mathcal{C}(P) \rightarrow \mathcal{C}(P)$ is

$$(\tau_v(g))(x) = \begin{cases} 1 - \max \left\{ \sum_{i=1}^k g(y_i) \mid (y_1, \dots, y_k) \in \text{MC}_v(P) \right\} & \text{if } x = v \\ g(x) & \text{if } x \neq v \end{cases}$$

We have the following generalizations of complementation Θ , down-transfer ∇ , and up-transfer Δ (and their inverses) to the piecewise-linear realm. In fact the term “down-transfer” was chosen as it is equivalent here to Stanley’s transfer map, used to transfer properties (such as volume formulas) between $\mathcal{C}(P)$ and $\mathcal{OP}(P)$ [23].

DEFINITION 2.13 ([6, § 4]). The maps $\Theta : \mathbb{R}^P \rightarrow \mathbb{R}^P$, $\nabla : \mathcal{OP}(P) \rightarrow \mathcal{C}(P)$, $\Delta : \mathcal{OR}(P) \rightarrow \mathcal{C}(P)$, and their inverses are given as follows.

$$\begin{aligned} (\Theta f)(x) &= 1 - f(x) \\ (\nabla f)(x) &= f(x) - \max_{y < x} f(y) \quad (\text{with } f(\widehat{0}) = 0) \\ (\Delta f)(x) &= f(x) - \max_{y > x} f(y) \quad (\text{with } f(\widehat{1}) = 0) \\ (\nabla^{-1} f)(x) &= \max \left\{ f(y_1) + f(y_2) + \dots + f(y_k) : \widehat{0} < y_1 < y_2 < \dots < y_k = x \right\} \\ &= f(x) + \max_{y < x} (\nabla^{-1} f)(y) \\ (\Delta^{-1} f)(x) &= \max \left\{ f(y_1) + f(y_2) + \dots + f(y_k) : x = y_1 < y_2 < \dots < y_k < \widehat{1} \right\} \\ &= f(x) + \max_{y > x} (\Delta^{-1} f)(y). \end{aligned}$$

For any linear extension (x_1, x_2, \dots, x_n) of P , Einstein and Propp showed that piecewise-linear order rowmotion defined as $T_{x_1} T_{x_2} \dots T_{x_n}$ is equivalent to the composition $\Theta \circ \Delta^{-1} \circ \nabla$ (a consequence of their proof at the birational level). The first author showed that piecewise-linear antichain rowmotion can be defined either as $\tau_{x_n} \dots \tau_{x_2} \tau_{x_1}$ or as $\nabla \circ \Theta \circ \Delta^{-1}$, as in the combinatorial realm. For details, see [6, § 4, § 6] and [12, § 3.3, § 3.4].

2.5. BIRATIONAL DYNAMICS. We now detropicalize the piecewise-linear order toggles to birational toggles over an arbitrary field \mathbb{K} of characteristic zero in the usual way: replacing the max operation with addition, addition with multiplication, subtraction with division, and the additive identity 0 with the multiplicative identity 1. Additionally, we replace 1 with a generic fixed constant $C \in \mathbb{K}$. (The definition in [6] is slightly more general than we need here; set $\alpha = 1$ and $\omega = C$ in their version to get ours. In this paper, we will be primarily interested in birational antichain rowmotion, in which the two arbitrary constants α and ω would always appear together as ω/α ; thus, one constant C is sufficient.)

DEFINITION 2.14 ([6, Definition 5.1]). Let $\mathbb{K}^P := \{f : P \rightarrow \mathbb{K}\}$ be the set of \mathbb{K} -labelings of the elements of P . For $v \in P$, the birational order toggle at v is the birational map $T_v : \mathbb{K}^P \dashrightarrow \mathbb{K}^P$ given by

$$(T_v(f))(x) = \begin{cases} f(x) & \text{if } x \neq v \\ \frac{\sum_{y \in P, y < v} f(y)}{f(v) \sum_{y \in P, y > v} \frac{1}{f(y)}} & \text{if } x = v \end{cases}$$

where we set $f(\widehat{0}) = 1$ and $f(\widehat{1}) = C$.

The birational order toggles $\{T_v : v \in P\}$ generate the *birational order toggle group*, a subgroup of the group of birational automorphisms of \mathbb{K}^P , which we denote $\text{BTog}_O(P)$. The following shows that basic properties of order-ideal toggles lift to the birational realm.

PROPOSITION 2.15 ([6, 8]). Each toggle T_v is an involution (i.e. T_v^2 is the identity). Two toggles T_u, T_v commute if and only if neither u nor v covers the other.

DEFINITION 2.16 ([6, Definition 5.2]). Let (x_1, x_2, \dots, x_n) be any linear extension of P . The birational analogue of order filter rowmotion, which we will call *birational order rowmotion* (or BOR-motion), is $\text{BOR} = T_{x_1} T_{x_2} \cdots T_{x_n}$. (Compare with Proposition 2.5.)

An annoying technicality here is that for some choices of labels it is possible that these maps could lead to division by zero. But for “generic” choices of labels (say with respect to the Zariski topology) iterates of this map will be well-defined. This is discussed carefully in [9, § 1] and [8, § 3]. Alternatively, Einstein and Propp make the choice to consider only *positive* labelings, i.e. $(\mathbb{R}_{>0})^{\widehat{P}}$.

2.6. BIRATIONAL TRANSFER MAPS. By detropicalizing the operations in the transfer maps of the previous subsection, we get their birational analogues. Einstein and Propp prove [6, § 6] that, under the definitions below, $\text{BOR} = \Theta \circ \Delta^{-1} \circ \nabla$. These maps are composed in the order which lifts combinatorial rowmotion on *order filters*.

DEFINITION 2.17 ([6, § 6]). Let $f \in \mathbb{K}^P$ and $x \in P$. We define the following birational maps. Again, we call Θ complement, ∇ down transfer, and Δ up transfer.

$$\begin{aligned} (\Theta f)(x) &= \frac{C}{f(x)} \\ (\nabla f)(x) &= \frac{f(x)}{\sum_{y < x} f(y)} \quad (\text{with } f(\widehat{0}) = 1) \\ (\Delta f)(x) &= \frac{f(x)}{\sum_{y > x} f(y)} \quad (\text{with } f(\widehat{1}) = 1) \end{aligned}$$

$$\begin{aligned}
 (\nabla^{-1}f)(x) &= \sum_{\widehat{0} \leq y_1 < y_2 < \dots < y_k = x} f(y_1)f(y_2) \cdots f(y_k) = f(x) \sum_{y < x} (\nabla^{-1}f)(y) \\
 (\Delta^{-1}f)(x) &= \sum_{x = y_1 < y_2 < \dots < y_k < \widehat{1}} f(y_1)f(y_2) \cdots f(y_k) = f(x) \sum_{y > x} (\Delta^{-1}f)(y).
 \end{aligned}$$

We use the same symbols in each realm (combinatorial, piecewise-linear, birational, and noncommutative), allowing context to clarify which is meant. Examples of each map ∇ , ∇^{-1} , Δ , and Δ^{-1} are given in Figure 1.

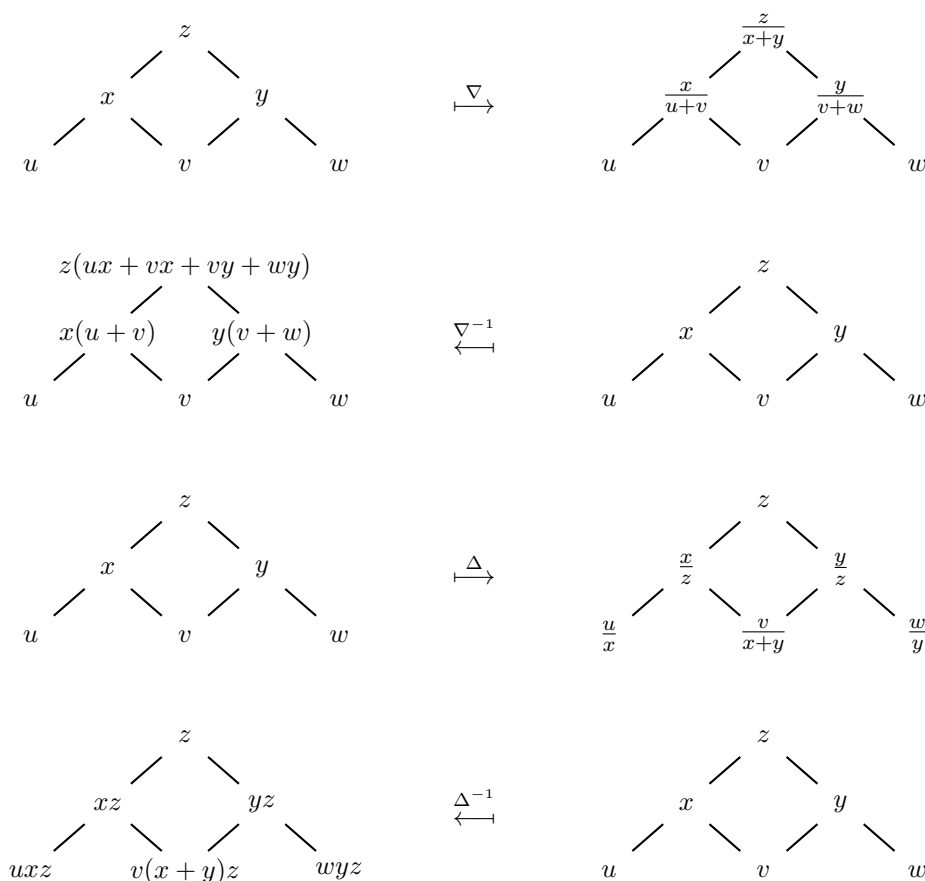


FIGURE 1. An example of each of the birational maps ∇ , ∇^{-1} , Δ , and Δ^{-1} on the positive root poset $\Phi^+(A_3)$.

3. BIRATIONAL ANTICHAIN TOGGLING AND ROWMOTION

3.1. THE BIRATIONAL ANTICHAIN TOGGLE GROUP. Now we will combine the different generalizations of toggling and study a new birational analogue of antichain toggling and rowmotion. Again, we fix a field \mathbb{K} of characteristic zero. In the combinatorial realm, we could define rowmotion on $\mathcal{J}(P)$ or $\mathcal{A}(P)$ either as a composition of the three maps Θ , Δ^{-1} , and ∇ (as is commonly done) or in terms of toggles, since these approaches are proven equivalent. BOR is usually defined in terms of toggles, and we take the analogous approach to defining BAR below, lifting the definition in Proposition 2.8.

DEFINITION 3.1. For $v \in P$ and $g \in \mathbb{K}^P$, set

$$\Upsilon_v g = \sum_{(y_1, \dots, y_k) \in \text{MC}_v(P)} g(y_1) \cdots g(y_k),$$

where we recall $\text{MC}_v(P)$ is the set of all maximal chains of P through v .

DEFINITION 3.2. Let $v \in P$. The birational antichain toggle is the birational map $\tau_v : \mathbb{K}^P \dashrightarrow \mathbb{K}^P$ defined as follows:

$$(\tau_v(g))(x) = \begin{cases} \frac{C}{\sum_{(y_1, \dots, y_k) \in \text{MC}_v(P)} g(y_1) \cdots g(y_k)} = \frac{C}{\Upsilon_v g} & \text{if } x = v \\ g(x) & \text{if } x \neq v. \end{cases}$$

This definition is what is obtained from Definition 2.12 through detropicalization of operations. As with antichain toggles in the combinatorial and piecewise-linear realms [26, 12], birational antichain toggles do not commute as frequently as order toggles.

PROPOSITION 3.3. Let $u, v \in P$.

- (a) Each toggle τ_v is an involution, i.e. τ_v^2 is the identity.
- (b) If $u \parallel v$ (i.e. u and v are incomparable), then $\tau_u \tau_v = \tau_v \tau_u$.

Proof. (a) Let $g \in \mathbb{K}^P$ be a generic labeling. To show τ_v is an involution, we wish to show $\tau_v^2(g) = g$. Since τ_v can only change the label at v , we need only show $(\tau_v^2(g))(v) = g(v)$. Every chain in $\text{MC}_v(P)$ can be split into segments: below v , v itself, and above v . As we can take the sums of products on each segment,

$$(1) \quad (\tau_v(g))(v) = \frac{C}{\left(\sum_{u \triangleleft v} (\nabla^{-1}g)(v)\right) g(v) \left(\sum_{u \triangleright v} (\Delta^{-1}g)(v)\right)}$$

for any $g \in \mathbb{K}^P$. In Eq. (1), we regard $\sum_{u \triangleleft v} (\nabla^{-1}g)(v) = 1$ if v is minimal in P and likewise $\sum_{u \triangleright v} (\Delta^{-1}g)(v) = 1$ if v is maximal in P (since the sums are nonempty when working in \hat{P}).

Using Eq. (1),

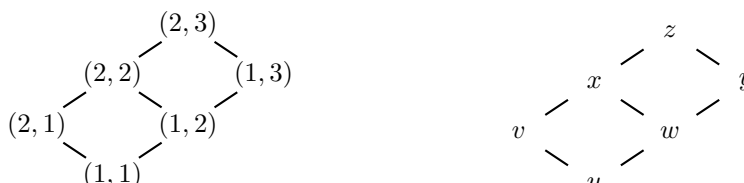
$$\begin{aligned} (\tau_v^2(g))(v) &= \frac{C}{\left(\sum_{u \triangleleft v} (\nabla^{-1}\tau_v(g))(v)\right) (\tau_v(g))(v) \left(\sum_{u \triangleright v} (\Delta^{-1}\tau_v(g))(v)\right)} \\ &= \frac{C}{\left(\sum_{u \triangleleft v} (\nabla^{-1}g)(v)\right) \frac{C}{\left(\sum_{u \triangleleft v} (\nabla^{-1}g)(v)\right) g(v) \left(\sum_{u \triangleright v} (\Delta^{-1}g)(v)\right)} \left(\sum_{u \triangleright v} (\Delta^{-1}g)(v)\right)} \\ &= g(v). \end{aligned}$$

(b) Suppose $u \parallel v$. Only the label of u can be changed by τ_u and only the label of v can be changed by τ_v . No chain contains both u and v , so the label of u has no effect on what τ_v does and the label of v has no effect on what τ_u does. So $\tau_u \tau_v = \tau_v \tau_u$. \square

Proposition 3.3 shows that the following definition is well-defined, since any two linear extensions of a poset differ by a sequence of transpositions of incomparable elements [7].

DEFINITION 3.4. Let (x_1, x_2, \dots, x_n) be any linear extension of a finite poset P . Then the birational map $\text{BAR} = \tau_{x_n} \cdots \tau_{x_2} \tau_{x_1}$, i.e. toggling once at each element of P from bottom to top, is called birational antichain rowmotion (BAR-motion).

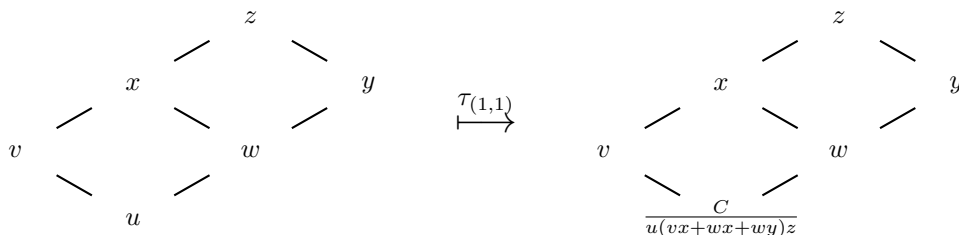
EXAMPLE 3.5. Consider the poset $P = [2] \times [3]$ below, with the generic labeling $g \in \mathbb{K}^P$ by $u, v, w, x, y, z \in \mathbb{K}$.



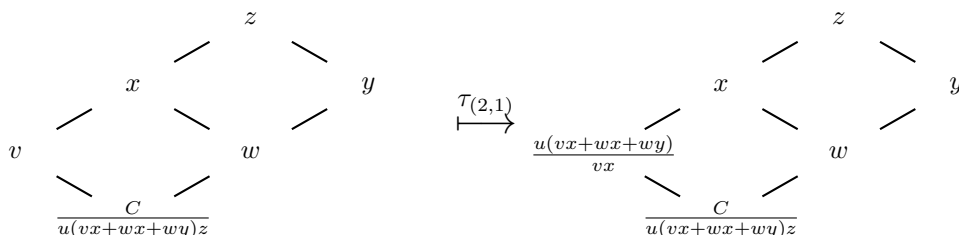
To compute BAR along the linear extension $(1, 1), (2, 1), (1, 2), (2, 2), (1, 3), (2, 3)$, we first toggle at $(1, 1)$. There are three maximal chains through this bottom element:

- $(1, 1) < (2, 1) < (2, 2) < (2, 3)$ with product of labels $uvxz$;
- $(1, 1) < (1, 2) < (2, 2) < (2, 3)$ with product of labels $uwxz$;
- $(1, 1) < (1, 2) < (1, 3) < (2, 3)$ with product of labels $uwyz$.

For $\Upsilon_{(1,1)}g$, we add up the products of the labels on these three maximal chains, and get $uvxz + uwxz + uwyz = u(vx + wx + wy)z$. Then to apply the toggle $\tau_{(1,1)}$, we change the label of $(1, 1)$ from u to $\frac{C}{u(vx+wx+wy)z}$.

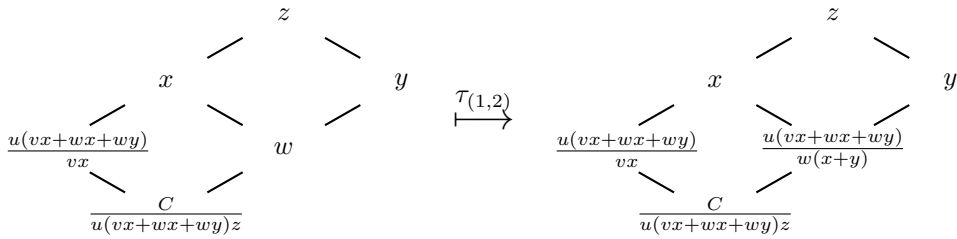


Now we apply $\tau_{(2,1)}$ to $\tau_{(1,1)}g$ (our above result). There is only one maximal chain through $(2, 1)$. The product of labels along that maximal chain is $\Upsilon_{(2,1)}(\tau_{(1,1)}g) = \frac{C}{u(vx+wx+wy)z} vxz$. Thus we change the label of $(2, 1)$ from v to $\frac{u(vx+wx+wy)}{vx}$.

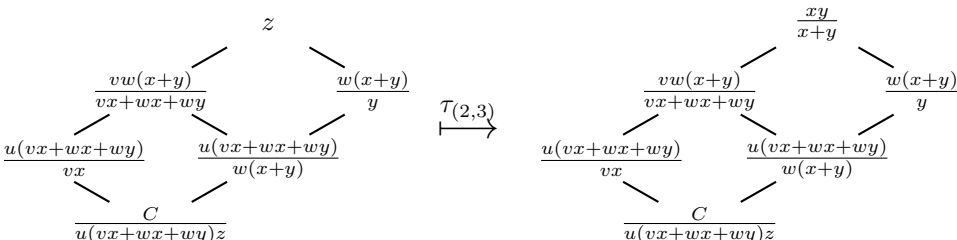
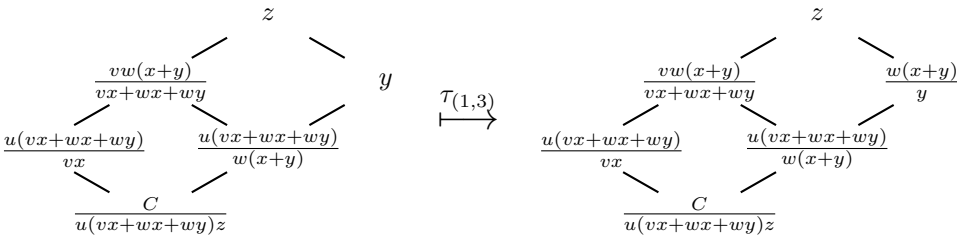
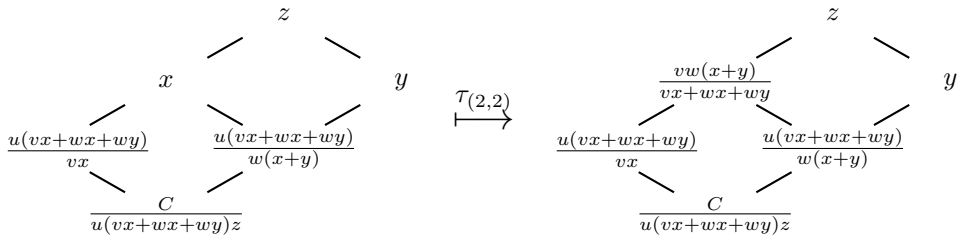


Next there are two maximal chains through $(1, 2)$, one of which goes through the element labeled x and the other through the element labeled y . Dividing C by the sum of the products of the labels for both chains gives

$$\frac{C}{\frac{C}{u(vx+wx+wy)z} w(x+y)z} = \frac{u(vx + wx + wy)}{w(x + y)}$$



Similarly, the remaining 3 toggles give



Note this composition of the six toggles is *one* iteration of BAR-motion on g .

THEOREM 3.6. *On a finite poset P , $\text{BAR} = \nabla \circ \Theta \circ \Delta^{-1}$, and the diagram below commutes.*

$$\begin{array}{ccc}
 \mathbb{K}^P & \xrightarrow{\text{BOR}} & \mathbb{K}^P \\
 \nabla \downarrow & & \downarrow \nabla \\
 \mathbb{K}^P & \xrightarrow{\text{BAR}} & \mathbb{K}^P
 \end{array}$$

Compare the example in Figure 2 to Example 3.5. We will not prove Theorem 3.6 now as it follows immediately from the more general noncommutative version: Theorem 5.26.

EXAMPLE 3.7. Since $\text{BOR} = \nabla^{-1} \circ \text{BAR} \circ \nabla$, BAR has the same order as BOR on any given finite poset P . On a general poset P , these birational rowmotion maps usually have infinite order, but on several nice families of posets described in [8, 9, 11], the order is finite (and the same as the order in the combinatorial realm). For example,

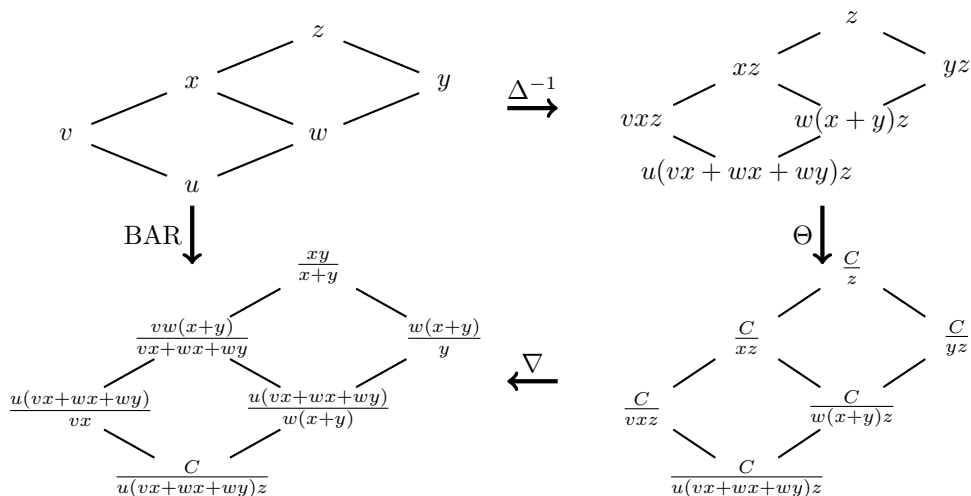


FIGURE 2. One iteration of BAR-motion on $[2] \times [3]$ as the composition of the three maps.

on a rectangle $[a] \times [b]$, birational rowmotion has order $a + b$. Figure 3 illustrates this with a generic orbit of BAR on $P = [2] \times [3]$, observing that the order is 5.

3.2. ISOMORPHISM BETWEEN THE TWO BIRATIONAL TOGGLE GROUPS. The first author constructed an explicit isomorphism between the combinatorial toggle groups of order ideals and of antichains, and then lifted it to the piecewise-linear realm [12]. Here we further lift it to the birational realm. It turns out that this isomorphism can be lifted even further to the noncommutative realm, with modified definitions because toggles are no longer involutions there. We do this in Section 5. All the proofs over skew fields imply the commutative birational counterparts by restriction. So in this subsection we merely state these (new) results.

DEFINITION 3.8. For $v \in P$, let $T_v^* = \tau_{v_1} \tau_{v_2} \cdots \tau_{v_k} \tau_v \tau_{v_k} \cdots \tau_{v_2} \tau_{v_1}$ where v_1, \dots, v_k are the elements of P covered by v . (In the case that v is a minimal element of P , $k = 0$ and $T_v^* = \tau_v$.) So T_v^* is the conjugation of τ_v by $\prod_{w < v} \tau_w$, which within $\text{BTog}_A(P)$ mimics the effect of the order toggle T_v .

THEOREM 3.9 (Analogue of [12, Thm. 2.15], generalized in Thm. 5.20). Let $v \in P$. Then the following diagram commutes on the domains in which the maps are defined.

$$\begin{array}{ccc}
 \mathbb{K}^P & \xrightarrow{T_v^*} & \mathbb{K}^P \\
 \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\
 \mathbb{K}^P & & \mathbb{K}^P \\
 \Theta \downarrow & & \downarrow \Theta \\
 \mathbb{K}^P & \xrightarrow{T_v} & \mathbb{K}^P
 \end{array}$$

EXAMPLE 3.10. Again we consider the poset $P = [2] \times [3]$ with elements named as in Example 3.5. Then $(2, 2)$ covers $(2, 1)$ and $(1, 2)$, so $T_{(2,2)}^* = \tau_{(2,1)} \tau_{(1,2)} \tau_{(2,2)} \tau_{(1,2)} \tau_{(2,1)}$. Since $(2, 1) \parallel (1, 2)$, the toggles $\tau_{(2,1)}$ and $\tau_{(1,2)}$ commute by Proposition 3.3, so we can apply them “simultaneously”. We verify Theorem 3.9 holds for this example in Figure 4.

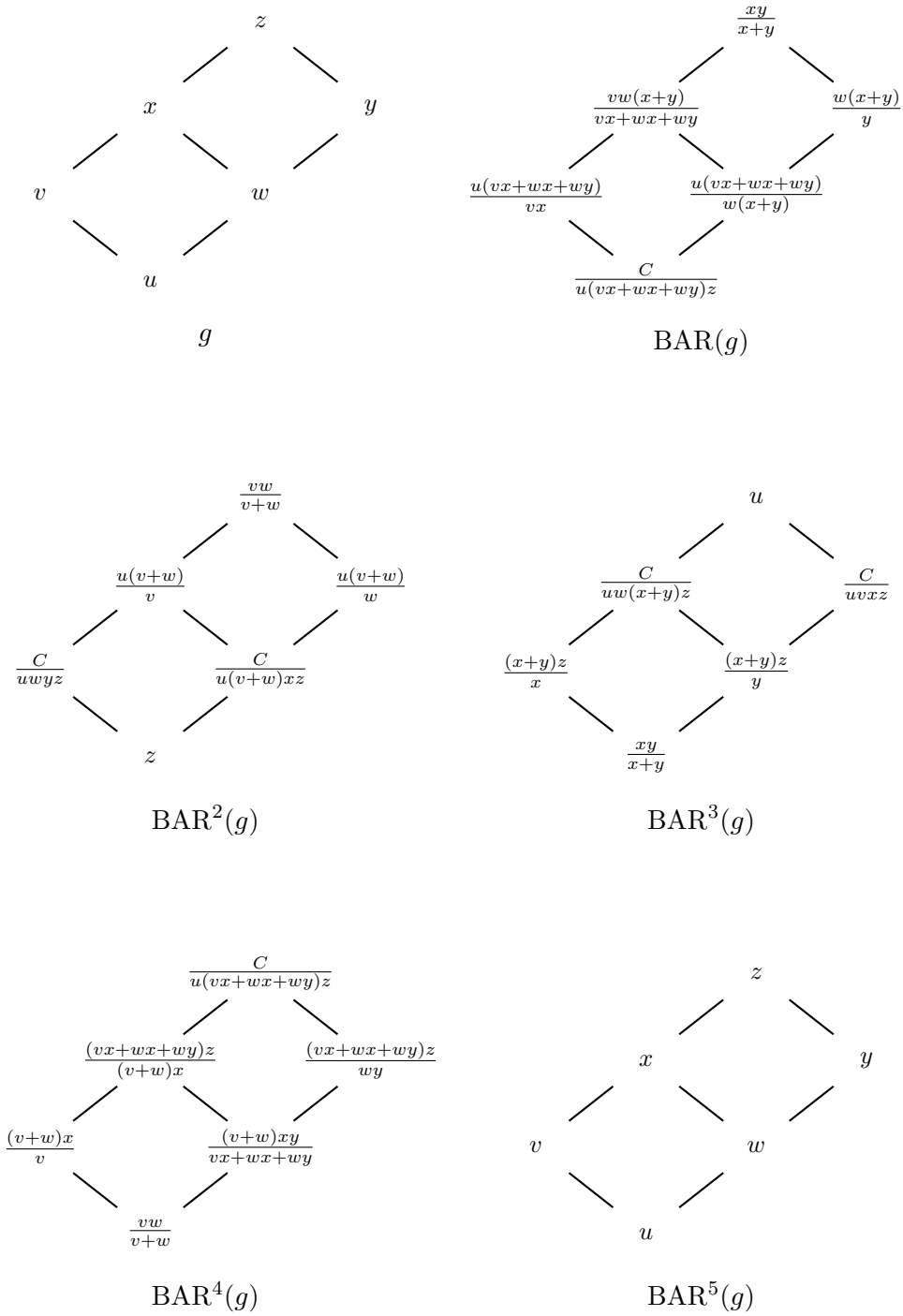


FIGURE 3. An orbit of BAR starting with a generic labeling $g \in \mathbb{K}^P$, for $P = [2] \times [3]$. We observe that $\text{BAR}^5(g) = g$, so the order of BAR is $5 = 2 + 3$ on this poset.

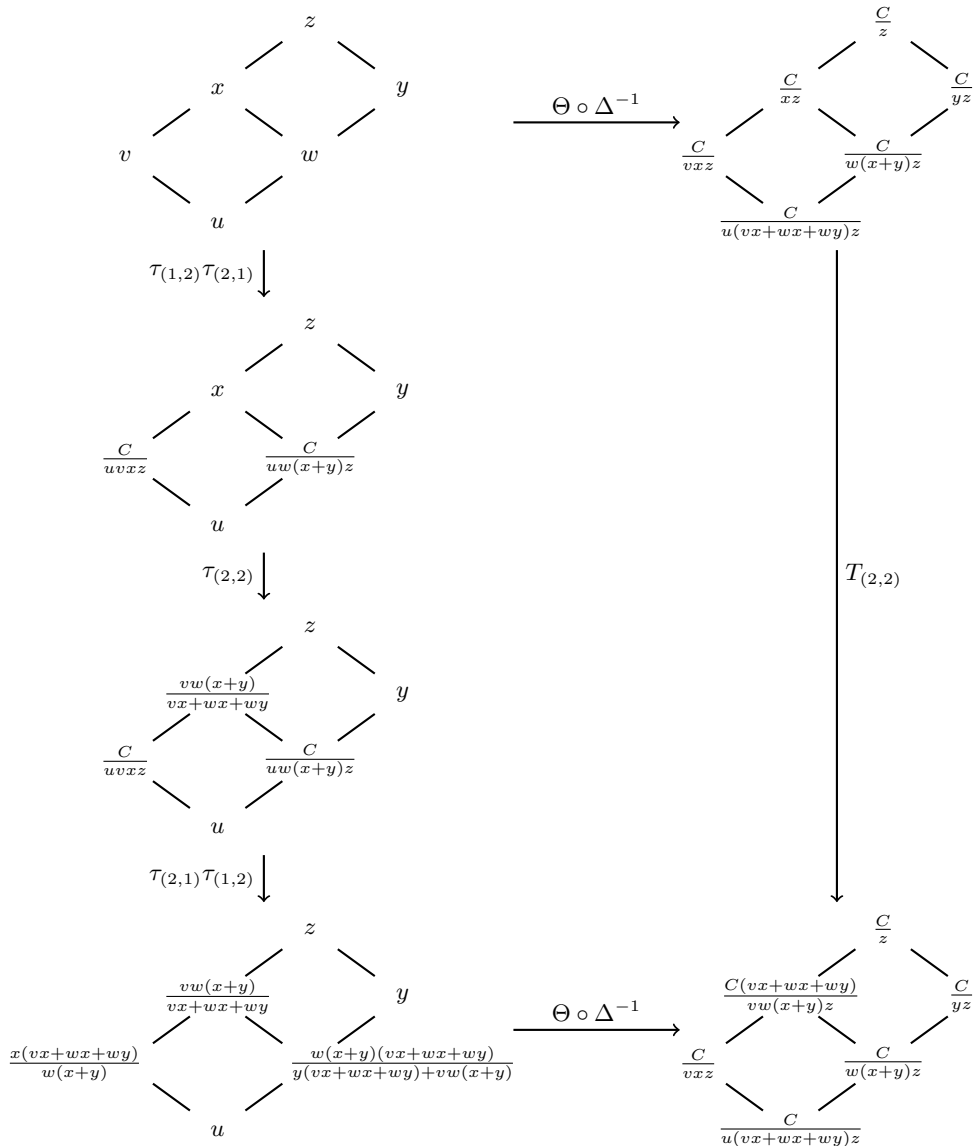


FIGURE 4. An illustration of Theorem 3.9. See Example 3.10.

DEFINITION 3.11. Let $v \in P$ and let (x_1, \dots, x_k) be a linear extension of the subposet $\{x \in P \mid x < v\}$ of P . Define $\eta_v = T_{x_1}T_{x_2} \cdots T_{x_k}$ and $\tau_v^* = \eta_v T_v \eta_v^{-1}$. (Note that η_v is well-defined since toggles corresponding to incomparable elements commute.)

As the next theorem formalizes, τ_v^* mimics the antichain toggle τ_v in terms of order toggles.

THEOREM 3.12 (Analogue of [12, Thm. 2.19], generalized in Thm. 5.23). *Let $v \in P$. Then the following diagram commutes on the domains in which the maps are defined.*

$$\begin{array}{ccc}
 \mathbb{K}^P & \overset{\tau_v}{\dashrightarrow} & \mathbb{K}^P \\
 \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\
 \mathbb{K}^P & & \mathbb{K}^P \\
 \Theta \downarrow & & \downarrow \Theta \\
 \mathbb{K}^P & \overset{\tau_v^*}{\dashrightarrow} & \mathbb{K}^P
 \end{array}$$

Theorems 3.9 and 3.12 yield the following corollary.

COROLLARY 3.13. *There is an isomorphism from $\text{BTog}_A(P)$ to $\text{BTog}_O(P)$ given by $\tau_v \mapsto \tau_v^*$ with inverse given by $T_v \mapsto T_v^*$.*

4. BIRATIONAL ANTICHAIN TOGGLES ON GRADED POSETS

4.1. TOGGING BY RANKS. Although rowmotion can be defined on any finite poset, only graded posets are currently known to have nice behavior (periodicity, homomesy, cyclic sieving, resonance). In fact, the name “rowmotion” references the natural factorization of this map as a product of rank (“row”) toggles in the graded case [27].

DEFINITION 4.1 ([24]). *A poset P is graded if it has a well-defined rank function $\text{rk} : P \rightarrow \mathbb{Z}_{\geq 0}$ satisfying*

- $\text{rk}(x) = 0$ for any minimal element x ,
- $\text{rk}(y) = \text{rk}(x) + 1$ if $y \succ x$,
- every maximal element x of P has $\text{rk}(x) = r$, where r is the rank of P .

For $x \in P$, we call $\text{rk}(x)$ the rank of x .

In this section, P will always refer to a finite graded poset of rank r .

DEFINITION 4.2. *Define birational antichain rank toggles as follows:*

$$\mathbf{T}_{\text{rk}=i} := \prod_{\text{rk}(x)=i} T_x, \quad \boldsymbol{\tau}_{\text{rk}=i} := \prod_{\text{rk}(x)=i} \tau_x, \quad \mathbf{T}_{\text{rk}=i}^* := \prod_{\text{rk}(x)=i} T_x^*, \quad \boldsymbol{\tau}_{\text{rk}=i}^* := \prod_{\text{rk}(x)=i} \tau_x^*.$$

Since poset elements of the same rank are pairwise incomparable, each product is of commuting toggles. Thus, the products above are all well-defined involutions.

Note

$$\text{BAR} = \boldsymbol{\tau}_{\text{rk}=r} \boldsymbol{\tau}_{\text{rk}=r-1} \cdots \boldsymbol{\tau}_{\text{rk}=1} \boldsymbol{\tau}_{\text{rk}=0} \quad \text{and} \quad \text{BOR} = \mathbf{T}_{\text{rk}=0} \mathbf{T}_{\text{rk}=1} \cdots \mathbf{T}_{\text{rk}=r-1} \mathbf{T}_{\text{rk}=r}.$$

Under the isomorphism between $\text{BTog}_A(P)$ and $\text{BTog}_O(P)$, the rank toggles get sent to products of rank toggles, as the following proposition shows. The proof in the piecewise-linear realm [12, Propositions 2.30, 2.31] goes through unchanged, so we omit it here.

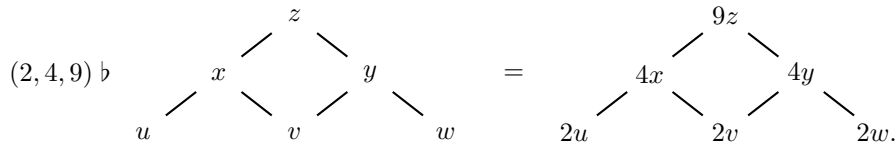
PROPOSITION 4.3. *Let $v \in P$ with $\text{rk}(v) = i$. We have the following identities involving rank toggles (where the empty product $\boldsymbol{\tau}_{\text{rk}=-1}$ is the identity).*

- $T_v^* = \boldsymbol{\tau}_{\text{rk}=i-1} \tau_v \boldsymbol{\tau}_{\text{rk}=i-1}$,
- $\mathbf{T}_{\text{rk}=i}^* = \boldsymbol{\tau}_{\text{rk}=i-1} \mathbf{T}_{\text{rk}=i} \boldsymbol{\tau}_{\text{rk}=i-1}$,
- $\tau_v^* = \mathbf{T}_{\text{rk}=0} \mathbf{T}_{\text{rk}=1} \cdots \mathbf{T}_{\text{rk}=i-1} T_v \mathbf{T}_{\text{rk}=i-1} \cdots \mathbf{T}_{\text{rk}=1} \mathbf{T}_{\text{rk}=0}$,
- $\boldsymbol{\tau}_{\text{rk}=i}^* = \mathbf{T}_{\text{rk}=0} \mathbf{T}_{\text{rk}=1} \cdots \mathbf{T}_{\text{rk}=i-1} \mathbf{T}_{\text{rk}=i} \mathbf{T}_{\text{rk}=i-1} \cdots \mathbf{T}_{\text{rk}=1} \mathbf{T}_{\text{rk}=0}$.

4.2. GRADED RESCALING. Grinberg and the second author analyzed the effect of BOR (and also birational order rank toggles) on graded rescalings of poset labelings, which highlighted the advantages of working with graded posets [9]. In this section, we give analogous results for the antichain analogues, describing how BAR and birational antichain rank toggles $\tau_{\text{rk}=i}$ act on graded rescalings.

DEFINITION 4.4 ([9, § 6]). Let $(a_0, \dots, a_r) \in (\mathbb{K}^\times)^{r+1}$ (where \mathbb{K}^\times denotes the nonzero elements of \mathbb{K}) and $g \in \mathbb{K}^P$. Then $(a_0, \dots, a_r) \flat g$ is the \mathbb{K} -labeling of P formed by taking g and multiplying the labels of all elements of rank i by a_i . This is called a graded rescaling of g by (a_0, \dots, a_r) .

EXAMPLE 4.5. In the positive root poset $\Phi^+(A_3)$



PROPOSITION 4.6. Let $g \in \mathbb{K}^P$ and $(a_0, \dots, a_r) \in (\mathbb{K}^\times)^{r+1}$. Then

$$\tau_{\text{rk}=i}((a_0, \dots, a_r) \flat g) = \left(a_0, \dots, a_{i-1}, \frac{1}{a_0 \cdots a_r}, a_{i+1}, \dots, a_r \right) \flat \tau_{\text{rk}=i}g.$$

The analogous result for birational order toggles [9, Prop. 39] has $\frac{a_{i-1}a_{i+1}}{a_i}$ in the i th position.

Proof. Let $h = (a_0, \dots, a_r) \flat g$. Let $v \in P$ have $\text{rk}(v) = i$. Then every maximal chain (y_0, \dots, y_r) in P contains one element from each rank level. Therefore,

$$\begin{aligned} \Upsilon_v h &= \sum_{(y_0, \dots, y_r) \in \text{MC}_v(P)} h(y_0)h(y_1) \cdots h(y_{r-1})h(y_r) \\ &= \sum_{(y_0, \dots, y_r) \in \text{MC}_v(P)} a_0g(y_0)a_1g(y_1) \cdots a_{r-1}g(y_{r-1})a_rg(y_r) \\ &= a_0a_1 \cdots a_r \sum_{(y_0, \dots, y_r) \in \text{MC}_v(P)} g(y_0)g(y_1) \cdots g(y_{r-1})g(y_r) \\ &= a_0a_1 \cdots a_r \Upsilon_v g. \end{aligned}$$

Then for every v of rank i ,

$$(\tau_{\text{rk}=i}h)(v) = \frac{C}{\Upsilon_v h} = \frac{C}{a_0a_1 \cdots a_r \Upsilon_v g} = \frac{1}{a_0a_1 \cdots a_r} (\tau_{\text{rk}=i}g)(v),$$

while for any x of rank $j \neq i$, $(\tau_{\text{rk}=i}h)(x) = h(x) = a_jg(x) = a_j(\tau_{\text{rk}=i}g)(x)$. Thus,

$$\tau_{\text{rk}=i}h = \left(a_0, \dots, a_{i-1}, \frac{1}{a_0 \cdots a_r}, a_{i+1}, \dots, a_r \right) \flat \tau_{\text{rk}=i}g. \quad \square$$

A straightforward induction argument shows the following analogue of [9, Prop. 40].

PROPOSITION 4.7. Let $g \in \mathbb{K}^P$ and $(a_0, \dots, a_r) \in (\mathbb{K}^\times)^{r+1}$. Then

$$\text{BAR}((a_0, a_1, \dots, a_r) \flat g) = \left(\frac{1}{a_0a_1 \cdots a_r}, a_0, a_1, \dots, a_{r-2}, a_{r-1} \right) \flat \text{BAR}(g).$$

The key idea is that, like BOR, applying BAR to a graded rescaling of g yields a graded rescaling of $\text{BAR}(g)$.

4.3. GYRATION. For a finite graded poset P , Striker defined an element of $\text{Tog}_{\mathcal{J}}(P)$ called *gyration*, which is conjugate to order-ideal rowmotion $\rho_{\mathcal{J}}$ [25, § 6]. The name *gyration* comes from Wieland’s action of the same name on alternating sign matrices [31]. Here we give a birational lifting of gyration using the same definition, which remains conjugate to BOR in $\text{Tog}_O(P)$ because the key algebraic properties of the order-ideal toggle group lift to the birational realm. In fact this idea goes back to Cameron and Fon-Der-Flaass, who considered (slightly more general) “rank-permuted rowmotions”, and showed that they were all conjugate in the order-ideal toggle group [3, Lemma 2].

DEFINITION 4.8. Birational order gyration is the birational map $\text{BOG} : \mathbb{K}^P \dashrightarrow \mathbb{K}^P$ that applies the birational order toggles for elements in even ranks first, then the odd ranks.

For example, if P has rank 7,

$$\text{BOG} = T_{\text{rk}=7} T_{\text{rk}=5} T_{\text{rk}=3} T_{\text{rk}=1} T_{\text{rk}=6} T_{\text{rk}=4} T_{\text{rk}=2} T_{\text{rk}=0}.$$

This is well-defined, since it does not matter in which order the elements of even rank are toggled, and similarly for odd rank. This is because rank toggles $T_{\text{rk}=i}, T_{\text{rk}=j}$ commute when $|i - j| \neq 1$, where there are no cover relations between an element of rank i and an element of rank j . Since BOR and BOG are conjugate in $\text{Tog}_O(P)$, they have the same order on any graded poset, and sometimes other properties can be transferred between the two maps.

On the other hand, birational *antichain* rank toggles never commute, so we need to specify a toggle order in the following definition. This definition of BAG is the image of BOG under our explicit isomorphism between $\text{BTog}_O(P)$ and $\text{BTog}_A(P)$.

DEFINITION 4.9. Birational antichain gyration is the birational map $\text{BAG} : \mathbb{K}^P \dashrightarrow \mathbb{K}^P$ that first applies the antichain toggles for odd ranks starting from the bottom of the poset up to the top, and then toggles the even ranks from the top of the poset down to the bottom.

For example, if P has rank 7, $\text{BAG} = \tau_{\text{rk}=0} \tau_{\text{rk}=2} \tau_{\text{rk}=4} \tau_{\text{rk}=6} \tau_{\text{rk}=7} \tau_{\text{rk}=5} \tau_{\text{rk}=3} \tau_{\text{rk}=1}$. We omit the proof of the following theorem here, which is completely analogous to [12, Theorem 2.34] but now lifted to the birational realm.

THEOREM 4.10. The following diagram commutes.

$$\begin{array}{ccc} \mathbb{K}^P & \overset{\text{BAG}}{\dashrightarrow} & \mathbb{K}^P \\ \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\ \mathbb{K}^P & & \mathbb{K}^P \\ \Theta \downarrow & & \downarrow \Theta \\ \mathbb{K}^P & \overset{\text{BOG}}{\dashrightarrow} & \mathbb{K}^P \end{array}$$

5. NONCOMMUTATIVE (SKEW FIELD) DYNAMICS

5.1. INTRODUCTION TO SKEW FIELD DYNAMICS. Darij Grinberg has conjectured that the periodicity of BOR-motion on certain nice posets continues to hold even when extended to labelings of P by elements that do not necessarily commute. Here we study the lifting to this setting of the antichain perspective and relate it to the order perspective. We first recall Grinberg’s original toggling definition of this map, which we call *NOR-motion*, and show that it is also given as a composition of three transfer maps as in the commutative case.

Next we define the antichain analogues of toggling and *NAR-motion*, which can also be given in terms of the transfer maps. Along the way we give an explicit isomorphism between the group of order toggles and the group of antichain toggles in the noncommutative case.

Let \mathbb{S} denote a *skew field* that contains an infinite field \mathbb{F} as a subfield. Any such skew field \mathbb{S} of characteristic zero satisfies this condition, as it contains an isomorphic copy of \mathbb{Q} . We will now work with \mathbb{S} -labelings in $\mathbb{S}^P := \{f : P \rightarrow \mathbb{S}\}$. We always require the generic constant $C \in \mathbb{S}$ to be in the *center* of \mathbb{S} (i.e. C commutes with every element of \mathbb{S}). The proofs in this section specialize to show the results of § 3.2.

NOTATION 5.1. For $x \in \mathbb{S}$, write \bar{x} for x^{-1} .

NOTATION 5.2. The (commutative and associative) operation *parallel sum* is defined by $x \# y = \overline{\bar{x} + \bar{y}}$. We use $\sum^\#$ as the analogue of \sum with $+$ replaced with $\#$.

The following *reciprocity* relation, analogous to one in [6, § 5], is easy to show.

PROPOSITION 5.3. For $x_1, \dots, x_n \in \mathbb{S}$,

$$\left(\sum_{i=1}^n \# x_i\right) \left(\sum_{i=1}^n \bar{x}_i\right) = \left(\sum_{i=1}^n \bar{x}_i\right) \left(\sum_{i=1}^n \# x_i\right) = 1.$$

REMARK 5.4. It can be quite tricky to simplify expressions in a skew field until one gains some experience. For example $x \# y = \overline{\bar{x} + \bar{y}}$ can equivalently be written as

- $\overline{y(x+y)x}$ by multiplying on the left by $y\bar{y}$ and the right by $\bar{x}x$ and using the property $\overline{AB} = \bar{B} \cdot \bar{A}$,
- or as $\overline{x(x+y)y}$ by multiplying on the left by $x\bar{x}$ and the right by $\bar{y}y$,

but is *not equivalent* to $\overline{yx(x+y)}$, $\overline{(x+y)xy}$, $\overline{xy(x+y)}$, or $\overline{(x+y)yx}$. We can simplify $\overline{yx(x+y)y}$ as

$$\overline{yx(x+y)y} = \overline{\bar{y}y(x+y)x} = \overline{(x+y)x}.$$

Many other expressions are more challenging to rewrite in equivalent forms. For example,

$$\overline{\bar{v} \cdot \bar{x} + \bar{w} \cdot \overline{(x+y)}} = (x+y)w \overline{(xv+xw+yw)xv} = xv \overline{(xv+xw+yw)}(x+y)w$$

and

$$\overline{(v+w) \cdot \bar{x} + \bar{w} \cdot \bar{y}} = yw \overline{(xv+xw+yw)x(v+w)} = x(v+w) \overline{(xv+xw+yw)}yw$$

are expressions that have arisen naturally in this study.

REMARK 5.5. When we move to the noncommutative setting, we no longer have the notions from algebraic geometry and commutative algebra of *Zariski topology* and *birational maps*, so we call the analogous maps *partial maps*. These maps will not be defined when expressions in the denominator (i.e. expression we take the inverse of) become zero, so the domains need to be restricted somehow. We do not try to address this issue formally, which would take us too far *afield*. In particular, all the maps we consider are noncommutative analogues of our earlier birational maps. At a minimum, any equalities stated will hold as birational identities whenever we restrict the variables to lie in the infinite subfield \mathbb{F} . Practically speaking, they will hold in much greater generality.

DEFINITION 5.6 (Darij Grinberg). Let $v \in P$. The noncommutative order toggle is the partial map $T_v : \mathbb{S}^P \dashrightarrow \mathbb{S}^P$ defined as follows. For this definition, we extend any

$f \in \mathbb{S}^P$ to a \widehat{P} -labeling by setting $f(\widehat{0}) = 1$ and $f(\widehat{1}) = C$, recalling C is in the center of \mathbb{S} . Then

$$(T_v(f))(w) = \begin{cases} \left(\sum_{u \in \widehat{P}, u < v} f(u) \right) \overline{f(v)} \left(\sum_{u \in \widehat{P}, u > v} f(u) \right) & \text{if } w = v \\ f(w) & \text{if } w \neq v. \end{cases}$$

Toggles in the noncommutative realm are *not involutions*, so it is surprising they have any nice features at all. Initially, the term “toggle” was chosen to be an involution, but we continue to use it here to keep terminology consistent with other realms. We will call the inverse of a toggle an *elggot*.

DEFINITION 5.7. Let $v \in P$. The noncommutative order elggot is the partial map $E_v : \mathbb{S}^P \dashrightarrow \mathbb{S}^P$ defined as follows. Then

$$(E_v(f))(w) = \begin{cases} \left(\sum_{u \in \widehat{P}, u > v} f(u) \right) \overline{f(v)} \left(\sum_{u \in \widehat{P}, u < v} f(u) \right) & \text{if } w = v \\ f(w) & \text{if } w \neq v. \end{cases}$$

A straightforward computation shows that T_v and E_v are inverse partial maps. Order toggles and elggots commute with each other in the skew-field setting exactly when they do in the (commutative) birational realm. We omit the elementary proof.

PROPOSITION 5.8. Let $u, v \in P$. If neither u nor v covers the other, then $T_u T_v = T_v T_u$, $E_u E_v = E_v E_u$, $T_u E_v = E_v T_u$, and $E_u T_v = T_v E_u$.

DEFINITION 5.9 (Darij Grinberg). Let (x_1, x_2, \dots, x_n) be any linear extension of a finite poset P . Then the partial map $\text{NOR} = T_{x_1} T_{x_2} \cdots T_{x_n}$ is called noncommutative order rowmotion (NOR-motion).

CONJECTURE 5.10 (Darij Grinberg). On $[a] \times [b]$, NOR has order $a + b$.

5.2. TRANSFER MAPS IN THE NONCOMMUTATIVE REALM.

DEFINITION 5.11. Let $f \in \mathbb{S}^P$. We define complement Θ , down transfer ∇ , up transfer Δ , inverse down transfer ∇^{-1} , and inverse up transfer Δ^{-1} as follows. These specialize to Definition 2.17 when \mathbb{S} is actually a field.

$$\begin{aligned} (\Theta f)(x) &= C \cdot \overline{f(x)} \\ (\nabla f)(x) &= f(x) \cdot \overline{\sum_{y < x} f(y)} \quad (\text{with } f(\widehat{0}) = 1) \\ (\Delta f)(x) &= \overline{\sum_{y > x} f(y)} \cdot f(x) \quad (\text{with } f(\widehat{1}) = 1) \\ (\nabla^{-1} f)(x) &= \sum_{\widehat{0} < y_1 < y_2 < \dots < y_k = x} f(y_k) \cdots f(y_2) f(y_1) = f(x) \cdot \sum_{y < x} (\nabla^{-1} f)(y) \\ (\Delta^{-1} f)(x) &= \sum_{x = y_1 < y_2 < \dots < y_k < \widehat{1}} f(y_k) \cdots f(y_2) f(y_1) = \sum_{y > x} (\Delta^{-1} f)(y) \cdot f(x). \end{aligned}$$

THEOREM 5.12 (Analogue of [6, Thm. 6.2]). For any finite poset P ,

$$\text{NOR} = \Theta \circ \Delta^{-1} \circ \nabla.$$

Proof. We will prove $(\Theta \Delta^{-1} \nabla f)(x) = (\text{NOR } f)(x)$ for all $x \in P$ for which either side is defined (recall these are partial maps). We induct on P from top to bottom. Let $x \in P$ and assume every $y > x$ satisfies the induction hypothesis.

Then

$$(\nabla f)(x) = f(x) \overline{\sum_{y < x} f(y)}.$$

Now we apply Δ^{-1} to both sides. Using the recursive description for Δ^{-1} , we obtain

$$\begin{aligned} (\Delta^{-1} \nabla f)(x) &= \sum_{y > x} (\Delta^{-1} \nabla f)(y) \cdot (\nabla f)(x) \\ &= \sum_{y > x} (\Delta^{-1} \nabla f)(y) \cdot f(x) \cdot \overline{\sum_{y < x} f(y)} \\ &= C \overline{\sum_{y > x}^{\#} (\Theta \Delta^{-1} \nabla f)(y) \cdot f(x) \cdot \sum_{y < x} f(y)}. \end{aligned}$$

Next we apply Θ to both sides, which yields

$$\begin{aligned} (\Theta \Delta^{-1} \nabla f)(x) &= C \cdot C \cdot \overline{\sum_{y > x}^{\#} (\Theta \Delta^{-1} \nabla f)(y) \cdot f(x) \cdot \sum_{y < x} f(y)} \\ &= \left(\sum_{y < x} f(y) \right) \cdot \overline{f(x)} \cdot \left(\sum_{y > x}^{\#} (\Theta \Delta^{-1} \nabla f)(y) \right) \\ &= \left(\sum_{y < x} f(y) \right) \cdot \overline{f(x)} \cdot \left(\sum_{y > x}^{\#} (\text{NOR } f)(y) \right) \end{aligned}$$

by the induction hypothesis. Note that the last expression equals $(\text{NOR } f)(x)$ because it is exactly what we obtain at x just before we toggle at x (where we have already toggled elements $y \succ x$ but *not* elements $y < x$). \square

5.3. NONCOMMUTATIVE ANTICHAIN TOGGING AND ROWMOTION.

DEFINITION 5.13. *Let $v \in P$. The noncommutative antichain toggle is the partial map $\tau_v : \mathbb{S}^P \dashrightarrow \mathbb{S}^P$ defined so that $(\tau_v(g))(x)$ equals*

$$C \cdot \sum \left\{ \overline{\begin{array}{cc} \underbrace{g(y_{c-1}) \cdots g(y_1)}_{(\text{indices decrease by } 1)} & \underbrace{g(y_k) \cdots g(y_c)}_{(\text{indices decrease by } 1)} \\ : \widehat{0} < y_1 < y_2 < \cdots < y_k < \widehat{1}, y_c = v \end{array}} \right\}$$

if $x = v$, and $(\tau_v(g))(x) = g(x)$ if $x \neq v$.

The noncommutative antichain elggot is the partial map $\varepsilon_v : \mathbb{S}^P \dashrightarrow \mathbb{S}^P$ defined so that as $(\varepsilon_v(g))(x)$ equals

$$C \cdot \sum \left\{ \overline{\begin{array}{cc} \underbrace{g(y_c) \cdots g(y_1)}_{(\text{indices decrease by } 1)} & \underbrace{g(y_k) \cdots g(y_{c+1})}_{(\text{indices decrease by } 1)} \\ : \widehat{0} < y_1 < y_2 < \cdots < y_k < \widehat{1}, y_c = v \end{array}} \right\}$$

if $x = v$, and $(\varepsilon_v(g))(x) = g(x)$ if $x \neq v$.

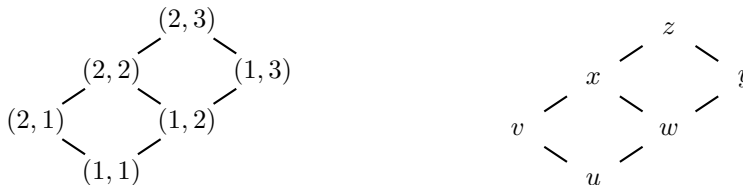
Let $\text{NTog}_A(P)$ be the group generated by all noncommutative antichain toggles τ_v for $v \in P$, and let $\text{NTog}_O(P)$ be the group generated by all noncommutative order toggles T_v .

Commutativity of toggles and elggot is the same as in the (commutative) birational realm.

PROPOSITION 5.14. *Let $u, v \in P$. If $u \parallel v$, then $\tau_u \tau_v = \tau_v \tau_u$, $\varepsilon_u \varepsilon_v = \varepsilon_v \varepsilon_u$, $\tau_u \varepsilon_v = \varepsilon_v \tau_u$.*

Proof. Analogous to the proof of Proposition 3.3(b). \square

EXAMPLE 5.15. Consider the poset $P = [2] \times [3]$ below, with the generic labeling $g \in \mathbb{K}^P$ by $u, v, w, x, y, z \in \mathbb{S}$.



- If we apply the toggle $\tau_{(1,1)}$, we would change the label at $(1, 1)$ to

$$C \cdot \overline{zxv u + zxw u + zyw u} = C \cdot \bar{u} \cdot \overline{(xv + xw + yw)} \cdot \bar{z}.$$

- If instead we apply the toggle $\tau_{(2,1)}$, we would change the label at $(2, 1)$ to

$$C \cdot \overline{uzxv} = C \cdot \bar{v} \cdot \bar{x} \cdot \bar{z} \cdot \bar{u}.$$

- If instead we apply the toggle $\tau_{(1,2)}$, we would change the label at $(1, 2)$ to

$$C \cdot \overline{uzxw + uz yw} = C \cdot \bar{w} \cdot \overline{(x + y)} \cdot \bar{z} \cdot \bar{u}.$$

- If instead we apply the toggle $\tau_{(2,2)}$, we would change the label at $(2, 2)$ to

$$C \cdot \overline{vuzx + wuzx} = C \cdot \bar{x} \cdot \bar{z} \cdot \bar{u} \cdot \overline{(v + w)}.$$

DEFINITION 5.16. Let (x_1, x_2, \dots, x_n) be any linear extension of a finite poset P . Then the partial map $\text{NAR} = \tau_{x_n} \cdots \tau_{x_2} \tau_{x_1}$, i.e. toggling at each element of P from bottom to top, is called noncommutative antichain rowmotion (NAR-motion).

EXAMPLE 5.17. On the poset $P = [2] \times [3]$, NAR has order 5. In Figure 5, we show an orbit beginning with a generic labeling.

We now define specific elements of $\text{NTog}_A(P)$ that mimic the action of order toggles.

DEFINITION 5.18. For $v \in P$, let $T_v^* = \varepsilon_{v_1} \varepsilon_{v_2} \cdots \varepsilon_{v_k} \tau_v \tau_{v_k} \cdots \tau_{v_2} \tau_{v_1} \in \text{NTog}_A(P)$ where v_1, \dots, v_k are the elements of P covered by v . (In the case that v is a minimal element of P , $k = 0$ and $T_v^* = \tau_v$.) Let $E_v^* = (T_v^*)^{-1} = \varepsilon_{v_1} \varepsilon_{v_2} \cdots \varepsilon_{v_k} \varepsilon_v \tau_{v_k} \cdots \tau_{v_2} \tau_{v_1}$.

The following lemma (whose proof is straightforward from the definitions) will be used in the proof of Theorem 5.20.

LEMMA 5.19. Let $g \in \mathbb{S}^P$ and $v \in P$. Then

$$\begin{aligned} (\tau_v g)(v) &= C \cdot \overline{(\nabla^{-1}g)(v)} \cdot \overline{(\Delta^{-1}g)(v)} \cdot g(v) \\ &= C \cdot \overline{(\Delta^{-1}g)(v)} \cdot \overline{(\nabla^{-1}g)(v)} \cdot g(v), \\ (\varepsilon_v g)(v) &= C \cdot g(v) \cdot \overline{(\nabla^{-1}g)(v)} \cdot \overline{(\Delta^{-1}g)(v)} \\ &= C \cdot g(v) \cdot \overline{(\Delta^{-1}g)(v)} \cdot \overline{(\nabla^{-1}g)(v)}. \end{aligned}$$

The following result uses the transfer maps to explicitly mimic the action of order toggles using the products of antichain toggles defined above and similarly for elgots.

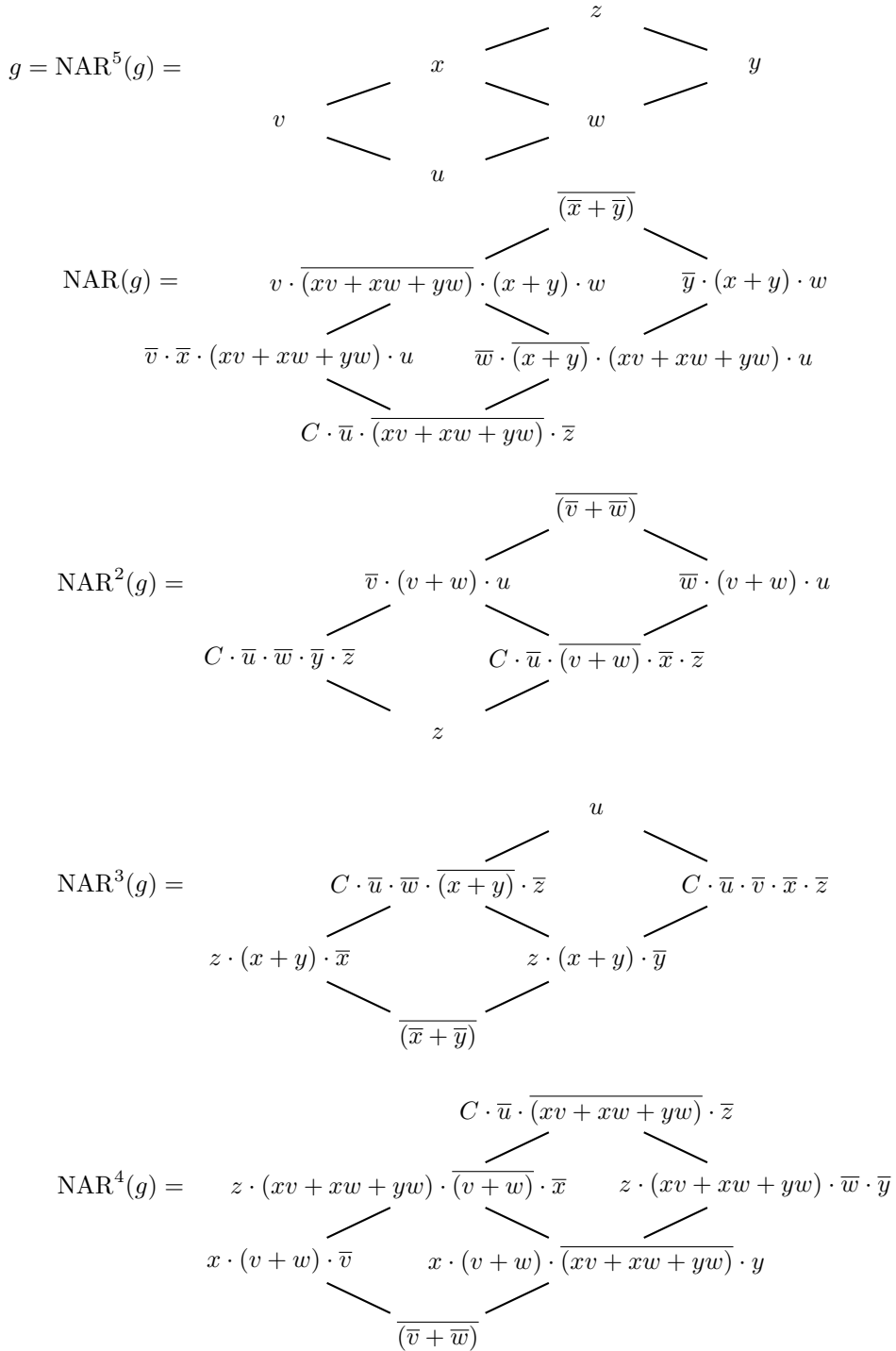


FIGURE 5. An orbit of NAR starting on a generic labeling $g \in \mathbb{S}^P$, for $P = [2] \times [3]$. We observe that the order of NAR, like BAR, is 5 on this poset.

THEOREM 5.20 (Analogue of Theorem 3.9). *Let $v \in P$. Then the following diagrams commute on the domains in which the maps are defined.*

$$\begin{array}{ccc}
 \mathbb{S}^P & \xrightarrow{T_v^*} & \mathbb{S}^P \\
 \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\
 \mathbb{S}^P & & \mathbb{S}^P \\
 \Theta \downarrow & & \downarrow \Theta \\
 \mathbb{S}^P & \xrightarrow{T_v} & \mathbb{S}^P
 \end{array}
 \qquad
 \begin{array}{ccc}
 \mathbb{S}^P & \xrightarrow{E_v^*} & \mathbb{S}^P \\
 \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\
 \mathbb{S}^P & & \mathbb{S}^P \\
 \Theta \downarrow & & \downarrow \Theta \\
 \mathbb{S}^P & \xrightarrow{E_v} & \mathbb{S}^P
 \end{array}$$

Proof. The right commutative diagram clearly follows from the left, so we will only prove the left one.

Let $g \in \mathbb{S}^P$. We must show that $\Theta\Delta^{-1}(T_v^*g) = T_v(\Theta\Delta^{-1}g)$.

Suppose v is a minimal element of P . Then $T_v^* = \tau_v$. Note from the definitions that

$$(\Theta\Delta^{-1}g)(x) = C \cdot \overline{\left\{g(y_k) \cdots g(y_2)g(y_1) : x = y_1 < y_2 < \cdots < y_k < \widehat{1}\right\}}.$$

Thus, $(\Theta\Delta^{-1}g)(x)$ only depends on the labels $g(y)$ for any $y \geq x$. Let $x \neq v$. Since τ_v only affects the label at v , and $x \not\leq v$ (by minimality of v), it follows that

$$(\Theta\Delta^{-1}(\tau_v g))(x) = (\Theta\Delta^{-1}g)(x) = (T_v(\Theta\Delta^{-1}g))(x).$$

Now we must confirm that $(\Theta\Delta^{-1}(\tau_v g))(v) = (T_v(\Theta\Delta^{-1}g))(v)$. We have

$$\begin{aligned}
 & (\Theta\Delta^{-1}(\tau_v g))(v) \\
 &= C \cdot \overline{(\Delta^{-1}(\tau_v g))(v)} \\
 &= C \cdot \overline{\sum_{y \geq v} (\Delta^{-1}(\tau_v g))(y) \cdot (\tau_v g)(v)} \\
 &= C \cdot \overline{\sum_{y \geq v} (\Delta^{-1}g)(y) \cdot (\tau_v g)(v)} \\
 &= C \cdot \overline{\sum_{y \geq v} (\Delta^{-1}g)(y) \cdot C \cdot \overline{(\Delta^{-1}g)(v)}} \quad (\text{definitions of } \tau_v \text{ and } \Delta^{-1} \text{ for minimal } v) \\
 &= C \cdot \overline{(\Delta^{-1}g)(v)} \left(\overline{C \cdot \sum_{y \geq v} (\Delta^{-1}g)(y)} \right) \\
 &= (\Theta\Delta^{-1}g)(v) \left(\sum_{y \geq v}^\# (\Theta\Delta^{-1}g)(y) \right) \\
 &= (T_v(\Theta\Delta^{-1}g))(v) \quad (v \text{ is minimal so there is no } y < v \text{ in } P).
 \end{aligned}$$

Now assume v is not minimal in P . Let v_1, \dots, v_k be the elements v covers. Let

$$\begin{aligned}
 g' &= \tau_v \tau_{v_k} \cdots \tau_{v_1} g, & g'' &= \varepsilon_{v_1} \cdots \varepsilon_{v_k} g' = T_v^* g, \\
 f &= \Theta\Delta^{-1}g, & f' &= \Theta\Delta^{-1}g', & f'' &= \Theta\Delta^{-1}g''.
 \end{aligned}$$

The goal is to show that $f'' = T_v f$. Note that g, g' , and g'' can only possibly differ in the labels of v, v_1, v_2, \dots, v_k . From the definitions of Θ and Δ^{-1} , we note that $T_v f$ and f'' can only possibly differ in the labels of elements $\leq v$.

We begin by proving $f''(v) = (T_v f)(v)$. Since v_1, \dots, v_k are pairwise incomparable (so each chain can only contain at most one of them), for $1 \leq j \leq k$,

$$\begin{aligned} (\tau_{v_1} \cdots \tau_{v_k} g)(v_j) &= C \cdot \overline{(\nabla^{-1}g)(v_j)} \cdot \overline{(\Delta^{-1}g)(v_j)} \cdot g(v_j) \quad (\text{from Lemma 5.19}) \\ &= C \cdot \overline{g(v_j)} \cdot \overline{(\nabla^{-1}g)(v_j)} \cdot \overline{(\Delta^{-1}g)(v_j)} \\ &= C \cdot \overline{\sum_{y \leq v_j} (\nabla^{-1}g)(v_j) \cdot (\Delta^{-1}g)(v_j)} \\ &= C \cdot \overline{(\Delta^{-1}g)(v_j)} \cdot \overline{\sum_{y \leq v_j} (\nabla^{-1}g)(v_j)} \\ &= f(v_j) \cdot \overline{\sum_{y \leq v_j} (\nabla^{-1}g)(v_j)}. \end{aligned}$$

We restate the above fact

$$(2) \quad (\tau_{v_1} \cdots \tau_{v_k} g)(v_j) = f(v_j) \cdot \overline{\sum_{y \leq v_j} (\nabla^{-1}g)(v_j)}$$

as an equation we will reference later.

Then to get $g'(v)$, we apply τ_v to $(\tau_{v_1} \cdots \tau_{v_k} g)(v)$. Lemma 5.19 gives

$$\begin{aligned} g''(v) = g'(v) &= C \cdot \overline{(\nabla^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(v)} \cdot \overline{(\Delta^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(v)} \cdot (\tau_{v_1} \cdots \tau_{v_k} g)(v) \\ &= C \cdot \overline{(\tau_{v_1} \cdots \tau_{v_k} g)(v)} \cdot \overline{(\nabla^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(v)} \cdot \overline{(\Delta^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(v)} \\ &= C \cdot \overline{\left(\sum_{v_j \leq v} (\nabla^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(v) \right)} \cdot \overline{(\Delta^{-1}g)(v)} \\ &= C \cdot \overline{(\Delta^{-1}g)(v)} \cdot \overline{\sum_{v_j \leq v} (\nabla^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(v)} \\ &= f(v) \cdot \overline{\sum_{v_j \leq v} (\nabla^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(v)} \\ &= f(v) \cdot \overline{\sum_{v_j \leq v} \left((\tau_{v_1} \cdots \tau_{v_k} g)(v_j) \sum_{y \leq v_j} (\nabla^{-1}(\tau_{v_1} \cdots \tau_{v_k} g))(y) \right)} \\ &= f(v) \cdot \overline{\sum_{v_j \leq v} \left((\tau_{v_1} \cdots \tau_{v_k} g)(v_j) \sum_{y \leq v_j} (\nabla^{-1}g)(y) \right)} \\ &= f(v) \cdot \overline{\sum_{v_j \leq v} \underbrace{f(v_j)}_{\text{from Eq. (2)}}}. \end{aligned}$$

Then using the recursive description of Δ^{-1} ,

$$\begin{aligned} f''(v) &= C \cdot \overline{(\Delta^{-1}g'')(v)} = C \cdot \overline{\sum_{y \geq v} (\Delta^{-1}g'')(v) \cdot g''(v)} = C \cdot \overline{\sum_{y \geq v} (\Delta^{-1}g)(y) \cdot g''(v)} \\ &= \overline{g''(v)} \cdot C \cdot \overline{\sum_{y \geq v} (\Delta^{-1}g)(y)} = \overline{g''(v)} \cdot \sum_{y \geq v} \#(\Theta \Delta^{-1}g)(y) \\ &= \overline{f(v)} \cdot \overline{\sum_{v_j \leq v} f(v_j)} \cdot \sum_{y \geq v} \#f(y) = \sum_{v_j \leq v} f(v_j) \cdot \overline{f(v)} \cdot \sum_{y \geq v} \#f(y) = (T_v f)(v). \end{aligned}$$

We noted earlier in the proof that $(T_v f)(x) = f''(x) = f(x)$ for all $x > v$. Now we have proven $(T_v f)(v) = f''(v)$. What remains to be shown is that $(T_v f)(x) = f''(x) = f(x)$ for all $x < v$, which we will now prove using downward induction on x . We begin with the base case $x < v$. For $1 \leq j \leq k$,

$$\begin{aligned}
 g''(v_j) &= (\varepsilon_{v_j} g')(v_j) \\
 &= C \cdot \overline{g'(v_j) \cdot (\nabla^{-1} g')(v_j) \cdot (\Delta^{-1} g')(v_j)} \quad (\text{from Lemma 5.19}) \\
 &= C \cdot \overline{(\nabla^{-1} g')(v_j) \cdot (\Delta^{-1} g')(v_j) \cdot g'(v_j)} \\
 &= C \cdot \overline{\left(g'(v_j) \sum_{y < v_j} (\nabla^{-1} g')(y) \right) \cdot \left(\sum_{y > v_j} (\Delta^{-1} g')(y) \cdot g'(v_j) \right) \cdot g'(v_j)} \\
 &= C \cdot \overline{g'(v_j) \cdot \sum_{y < v_j} (\nabla^{-1} g')(y) \cdot \sum_{y > v_j} (\Delta^{-1} g')(y)} \\
 &= f(v_j) \cdot \overline{\sum_{y < v_j} (\nabla^{-1} g)(v_j) \cdot \sum_{y < v_j} (\nabla^{-1} g')(y) \cdot \sum_{y > v_j} (\Delta^{-1} g')(y)} \quad (\text{from Eq. (2)}) \\
 &= f(v_j) \overline{\sum_{y > v_j} (\Delta^{-1} g')(y)} \\
 &= f(v_j) \overline{\sum_{y > v_j} (\Delta^{-1} g'')(y)}
 \end{aligned}$$

where the last equality is because $\Delta^{-1} g', \Delta^{-1} g''$ are the same for $y > v_j$. Using the above fact in the fourth equality below,

$$\begin{aligned}
 f''(v_j) &= C \cdot \overline{(\Delta^{-1} g'')(v_j)} = \overline{\sum_{y > v_j} (\Delta^{-1} g'')(y) \cdot g''(v_j)} = C \cdot \overline{g''(v_j)} \cdot \overline{\sum_{y > v_j} (\Delta^{-1} g'')(y)} \\
 &= f(v_j) \overline{\sum_{y > v_j} (\Delta^{-1} g'')(y)} \cdot \overline{\sum_{y > v_j} (\Delta^{-1} g'')(y)} = f(v_j) = (T_v f)(v_j).
 \end{aligned}$$

Now let $x < v$ and $x \notin \{v_1, \dots, v_k\}$. Assume that $(T_v f)(y) = f(y) = f''(y)$ for every y covering x (which cannot include $y = v$ because $x \notin \{v_1, \dots, v_k\}$). Also since $x \notin \{v, v_1, \dots, v_k\}$, recall that $g(x) = g''(x)$. So

$$\begin{aligned}
 f''(x) &= C \cdot \overline{(\Delta^{-1} g'')(x)} = C \cdot \overline{\sum_{y > x} (\Delta^{-1} g'')(y) \cdot g''(x)} = \overline{\sum_{y > x} (\Theta f'')(y) \cdot g''(x)} \\
 &= \overline{\sum_{y > x} (\Theta f)(y) \cdot g(x)} = \overline{\sum_{y > x} (\Delta^{-1} g)(y) \cdot g(x)} = \overline{(\Delta^{-1} g)(x)} = f(x) = (T_v f)(x). \quad \square
 \end{aligned}$$

We continue the group-theoretic approach of [12] to prove $\text{NAR} = \nabla \circ \Theta \circ \Delta^{-1}$. The proofs here are similar to those in [12], but modified as toggles are no longer involutions. The next two definitions and theorem allow us to mimic antichain toggles by order toggles.

DEFINITION 5.21. For $S \subseteq P$ let $\eta_S := T_{x_1} T_{x_2} \cdots T_{x_k}$ where (x_1, x_2, \dots, x_k) is a linear extension of the subposet $\{x \in P \mid x < y \text{ for some } y \in S\}$. (In the special case where every element of S is minimal in P , η_S is the identity.) For $v \in P$, we write $\eta_v := \eta_{\{v\}}$.

DEFINITION 5.22. For $v \in P$, define $\tau_v^* \in \text{NTog}_O(P)$ as $\tau_v^* := \eta_v T_v \eta_v^{-1}$. Let $\varepsilon_v^* = (\tau_v^*)^{-1} = \eta_v E_v \eta_v^{-1}$.

THEOREM 5.23 (Analogue of 3.12 and [12, Thm. 2.19]). *Let $v \in P$. Then the following diagrams commute on the domains in which the maps are defined.*

$$\begin{array}{ccc}
 \mathbb{S}^P & \overset{\tau_v}{\dashrightarrow} & \mathbb{S}^P \\
 \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\
 \mathbb{S}^P & & \mathbb{S}^P \\
 \Theta \downarrow & & \downarrow \Theta \\
 \mathbb{S}^P & \overset{\tau_v^*}{\dashrightarrow} & \mathbb{S}^P
 \end{array}
 \qquad
 \begin{array}{ccc}
 \mathbb{S}^P & \overset{\varepsilon_v}{\dashrightarrow} & \mathbb{S}^P \\
 \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\
 \mathbb{S}^P & & \mathbb{S}^P \\
 \Theta \downarrow & & \downarrow \Theta \\
 \mathbb{S}^P & \overset{\varepsilon_v^*}{\dashrightarrow} & \mathbb{S}^P
 \end{array}$$

To prove Theorem 5.23, we first need a lemma.

LEMMA 5.24 (Analogue of [12, Lemma 2.21]). *Let v_1, \dots, v_k be pairwise incomparable elements of P . Then for $1 \leq i \leq k$,*

$$\tau_{v_1}^* \tau_{v_2}^* \dots \tau_{v_i}^* = \eta_{\{v_1, \dots, v_i\}} T_{v_1} T_{v_2} \dots T_{v_i} \eta_{\{v_1, \dots, v_i\}}^{-1}.$$

Proof. This proof is similar to that of [12, Lemma 2.21].

This claim is true by definition for $i = 1$ and we proceed inductively. Suppose it is true for some given $i \leq k - 1$. Let

- x_1, \dots, x_a be the elements that are both less than v_{i+1} and less than at least one of v_1, \dots, v_i ,
- y_1, \dots, y_b be the elements that are less than at least one of v_1, \dots, v_i but not less than v_{i+1} ,
- z_1, \dots, z_c be the elements that are less than v_{i+1} but not less than any of v_1, \dots, v_i .

Clearly, it is possible for one or more of the sets $\{x_1, \dots, x_a\}$, $\{y_1, \dots, y_b\}$, and $\{z_1, \dots, z_c\}$ to be empty. For example, if $b = 0$, then the product $T_{y_1} \dots T_{y_b}$ is just the identity.

Note that none of y_1, \dots, y_b are less than any of x_1, \dots, x_a because any element less than some x_j is automatically less than v_{i+1} . By similar reasoning, none of z_1, \dots, z_c are less than any of x_1, \dots, x_a either. Also any pair y_m, z_n are incomparable, because $y_m \leq z_n$ would imply $y_m < v_{i+1}$, while $z_n \leq y_m$ would imply z_n is less than some v_j . By transitivity and the pairwise incomparability of v_1, \dots, v_{i+1} , each y_m is incomparable with v_{i+1} , and each z_m is incomparable with any of v_1, \dots, v_i .

We will pick the indices so that (x_1, \dots, x_a) , (y_1, \dots, y_b) , and (z_1, \dots, z_c) are linear extensions of the subposets $\{x_1, \dots, x_a\}$, $\{y_1, \dots, y_b\}$, and $\{z_1, \dots, z_c\}$, respectively. Then we have the following

- $(x_1, \dots, x_a, y_1, \dots, y_b)$ is a linear extension of $\{p \in P \mid p < q, q \in \{v_1, \dots, v_i\}\}$.
 – This yields $\eta_{\{v_1, \dots, v_i\}} = T_{x_1} \dots T_{x_a} T_{y_1} \dots T_{y_b}$.
- $(x_1, \dots, x_a, z_1, \dots, z_c)$ is a linear extension of $\{p \in P \mid p < v_{i+1}\}$.
 – This yields $\eta_{v_{i+1}} = T_{x_1} \dots T_{x_a} T_{z_1} \dots T_{z_c}$.
- $(x_1, \dots, x_a, y_1, \dots, y_b, z_1, \dots, z_c)$ and $(x_1, \dots, x_a, z_1, \dots, z_c, y_1, \dots, y_b)$ are both linear extensions of $\{p \in P \mid p < q, q \in \{v_1, \dots, v_{i+1}\}\}$.
 – This yields $\eta_{\{v_1, \dots, v_{i+1}\}} = T_{x_1} \dots T_{x_a} T_{y_1} \dots T_{y_b} T_{z_1} \dots T_{z_c}$.

Using the induction hypothesis,

$$\begin{aligned}
 & \tau_{v_1}^* \cdots \tau_{v_i}^* \tau_{v_{i+1}}^* \\
 &= \eta_{\{v_1, \dots, v_i\}} T_{v_1} \cdots T_{v_i} \eta_{\{v_1, \dots, v_i\}}^{-1} \eta_{v_{i+1}} T_{v_{i+1}} \eta_{v_{i+1}}^{-1} \\
 &= T_{x_1} \cdots T_{x_a} T_{y_1} \cdots T_{y_b} T_{v_1} \cdots T_{v_i} E_{y_b} \cdots E_{y_1} E_{x_a} \cdots E_{x_1} \\
 &\quad T_{x_1} \cdots T_{x_a} T_{z_1} \cdots T_{z_c} T_{v_{i+1}} E_{z_c} \cdots E_{z_1} E_{x_a} \cdots E_{x_1} \\
 &= T_{x_1} \cdots T_{x_a} T_{y_1} \cdots T_{y_b} T_{v_1} \cdots T_{v_i} E_{y_b} \cdots E_{y_1} T_{z_1} \cdots T_{z_c} T_{v_{i+1}} E_{z_c} \cdots E_{z_1} E_{x_a} \cdots E_{x_1} \\
 &= T_{x_1} \cdots T_{x_a} T_{y_1} \cdots T_{y_b} T_{v_1} \cdots T_{v_i} T_{z_1} \cdots T_{z_c} T_{v_{i+1}} E_{z_c} \cdots E_{z_1} E_{y_b} \cdots E_{y_1} E_{x_a} \cdots E_{x_1} \\
 &= T_{x_1} \cdots T_{x_a} T_{y_1} \cdots T_{y_b} T_{z_1} \cdots T_{z_c} T_{v_1} \cdots T_{v_i} T_{v_{i+1}} E_{z_c} \cdots E_{z_1} E_{y_b} \cdots E_{y_1} E_{x_a} \cdots E_{x_1} \\
 &= \eta_{\{v_1, \dots, v_{i+1}\}} T_{v_1} \cdots T_{v_i} T_{v_{i+1}} \eta_{\{v_1, \dots, v_{i+1}\}}^{-1}
 \end{aligned}$$

where each commutation above is between toggles/elggots for pairwise incomparable elements. \square

We are now ready to prove Theorem 5.23.

Proof of Theorem 5.23. The right commutative diagram clearly follows from the left, so we will simply prove the left.

We use induction on v . If v is a minimal element of P , then $\tau_v^* = T_v$ and $T_v^* = \tau_v$, so the diagram commutes by Theorem 5.20.

Now suppose v is not minimal. Let v_1, \dots, v_k be the elements of P covered by v , and suppose that the theorem is true for every v_i . That is, for every $A \in \mathbb{S}^P$ with $I = \Theta \Delta^{-1} A$, we have $\Theta \Delta^{-1}(\tau_{v_i}(A)) = \tau_{v_i}^*(I)$.

Then

$$\Theta \Delta^{-1}(\tau_{v_1} \tau_{v_2} \cdots \tau_{v_k}(A)) = \tau_{v_1}^* \tau_{v_2}^* \cdots \tau_{v_k}^*(I) = \eta_{\{v_1, \dots, v_k\}} T_{v_1} T_{v_2} \cdots T_{v_k} \eta_{\{v_1, \dots, v_k\}}^{-1}(I)$$

and

$$\Theta \Delta^{-1}(\varepsilon_{v_1} \varepsilon_{v_2} \cdots \varepsilon_{v_k}(A)) = \varepsilon_{v_1}^* \varepsilon_{v_2}^* \cdots \varepsilon_{v_k}^*(I) = \eta_{\{v_1, \dots, v_k\}} E_{v_1} E_{v_2} \cdots E_{v_k} \eta_{\{v_1, \dots, v_k\}}^{-1}(I)$$

by Lemma 5.24.

Throughout this proof, we let $A \in \mathbb{S}^P$ and $I = \Theta \Delta^{-1} A \in \mathbb{S}^P$. Think A for ‘‘antichain’’ and I as referring to ‘‘the order ideal generated by A ’’ if we were in the combinatorial realm.

From the definition of T_v^* , it follows that $\tau_{v_1} \tau_{v_2} \cdots \tau_{v_k} T_v^* \varepsilon_{v_k} \cdots \varepsilon_{v_2} \varepsilon_{v_1} = \tau_v$. Then

$$\begin{aligned}
 & \Theta \Delta^{-1}(\tau_v(A)) \\
 &= \Theta \Delta^{-1}(\tau_{v_1} \tau_{v_2} \cdots \tau_{v_k} T_v^* \varepsilon_{v_k} \cdots \varepsilon_{v_2} \varepsilon_{v_1}(A)) \\
 &= \eta_{\{v_1, \dots, v_k\}} T_{v_1} T_{v_2} \cdots T_{v_k} \eta_{\{v_1, \dots, v_k\}}^{-1} T_v \eta_{\{v_1, \dots, v_k\}} E_{v_k} \cdots E_{v_2} E_{v_1} \eta_{\{v_1, \dots, v_k\}}^{-1}(I)
 \end{aligned}$$

by Theorem 5.20 (for T_v^*) and the induction hypothesis (for $\tau_{v_1} \tau_{v_2} \cdots \tau_{v_k}$ and $\varepsilon_{v_k} \cdots \varepsilon_{v_2} \varepsilon_{v_1}$). Thus, it suffices to show that

$$(3) \quad \eta_{\{v_1, \dots, v_k\}} T_{v_1} T_{v_2} \cdots T_{v_k} \eta_{\{v_1, \dots, v_k\}}^{-1} T_v \eta_{\{v_1, \dots, v_k\}} E_{v_k} \cdots E_{v_2} E_{v_1} \eta_{\{v_1, \dots, v_k\}}^{-1} = \tau_v^*.$$

The toggles in the product $\eta_{\{v_1, \dots, v_k\}}$ correspond to elements strictly less than v_1, \dots, v_k ; none of these cover nor are covered by v . Thus we can commute T_v with $\eta_{\{v_1, \dots, v_k\}}$ on the left side of (3) and then cancel $\eta_{\{v_1, \dots, v_k\}}^{-1} \eta_{\{v_1, \dots, v_k\}}$. Thus the left side of (3) is

$$\eta_{\{v_1, \dots, v_k\}} T_{v_1} T_{v_2} \cdots T_{v_k} T_v E_{v_k} \cdots E_{v_2} E_{v_1} \eta_{\{v_1, \dots, v_k\}}^{-1}.$$

Note that

$$\{x \in P \mid x < v\} = \{x \in P \mid x < y \text{ for some } y \in \{v_1, \dots, v_k\}\} \cup \{v_1, \dots, v_k\}$$

where the union is disjoint and that v_1, \dots, v_k are maximal elements of this set. Thus for any linear extension (x_1, \dots, x_n) of $\{x \in P \mid x < y \text{ for some } y \in \{v_1, \dots, v_k\}\}$, a linear extension of $\{x \in P \mid x < v\}$ is $(x_1, \dots, x_n, v_1, \dots, v_k)$. So $\eta_{\{v_1, \dots, v_k\}} T_{v_1} T_{v_2} \cdots T_{v_k} = \eta_v$ and $E_{v_k} \cdots E_{v_2} E_{v_1} \eta_{\{v_1, \dots, v_k\}}^{-1} = \eta_v^{-1}$ which means the left side of (3) is $\eta_v T_v \eta_v^{-1} = \tau_v^*$, the same as the right side. \square

The following is a corollary of Theorems 5.20 and 5.23.

COROLLARY 5.25. *There is an isomorphism from $\text{NTog}_A(P)$ to $\text{NTog}_O(P)$ given by $\tau_v \mapsto \tau_v^*$, with inverse given by $T_v \mapsto T_v^*$.*

THEOREM 5.26. *For any finite poset P , $\text{NAR} = \nabla \circ \Theta \circ \Delta^{-1}$.*

Proving Theorem 5.26 is equivalent to proving the following diagram commutes on the domains in which the maps are defined. This is because of Theorem 5.12 which says $\text{NOR} = \Theta \circ \Delta^{-1} \circ \nabla$.

$$\begin{array}{ccc}
 \mathbb{S}^P & \xrightarrow{\text{NAR}} & \mathbb{S}^P \\
 \Delta^{-1} \downarrow & & \downarrow \Delta^{-1} \\
 \mathbb{S}^P & & \mathbb{S}^P \\
 \Theta \downarrow & & \downarrow \Theta \\
 \mathbb{S}^P & \xrightarrow{\text{NOR}} & \mathbb{S}^P
 \end{array}$$

Since $\text{NOR} = \Theta \circ \Delta^{-1} \circ \nabla$, this leads to the following simpler commutative diagram.

$$\begin{array}{ccc}
 \mathbb{S}^P & \xrightarrow{\text{NOR}} & \mathbb{S}^P \\
 \nabla \downarrow & & \downarrow \nabla \\
 \mathbb{S}^P & \xrightarrow{\text{NAR}} & \mathbb{S}^P
 \end{array}$$

Proof. This proof is similar to the proof of [12, Theorem 3.21].

Let (x_1, x_2, \dots, x_n) be any linear extension of a finite poset P . By the definitions, $\text{NAR} = \tau_{x_n} \cdots \tau_{x_2} \tau_{x_1}$ and $\text{NOR} = T_{x_1} T_{x_2} \cdots T_{x_n}$.

Using the isomorphism from $\text{NTog}_A(P)$ to $\text{NTog}_O(P)$ given by $\tau_v \mapsto \tau_v^*$, it suffices to show that $\tau_{x_n}^* \cdots \tau_{x_2}^* \tau_{x_1}^* = \text{NOR} = T_{x_1} T_{x_2} \cdots T_{x_n}$. We will use induction to prove that $\tau_{x_k}^* \cdots \tau_{x_2}^* \tau_{x_1}^* = T_{x_1} T_{x_2} \cdots T_{x_k}$ for $1 \leq k \leq n$.

For the base case, $\tau_{x_1}^* = T_{x_1}$ since x_1 is a minimal element of P . For the induction hypothesis, let $1 \leq k \leq n - 1$ and assume that $\tau_{x_k}^* \cdots \tau_{x_2}^* \tau_{x_1}^* = T_{x_1} T_{x_2} \cdots T_{x_k}$. Then

$$(4) \quad \tau_{x_{k+1}}^* \tau_{x_k}^* \cdots \tau_{x_2}^* \tau_{x_1}^* = \eta_{x_{k+1}} T_{x_{k+1}} \eta_{x_{k+1}}^{-1} T_{x_1} T_{x_2} \cdots T_{x_k}$$

Let $(y_1, \dots, y_{k'})$ be a linear extension of the subposet $\{y \in P \mid y < x_{k+1}\}$ of P . Then since (x_1, \dots, x_n) is a linear extension of P , all of $y_1, \dots, y_{k'}$ must be in $\{x_1, \dots, x_k\}$. Furthermore, any element less than one of $y_1, \dots, y_{k'}$ must be less than x_{k+1} so none of the elements of $\{x_1, \dots, x_k\}$ outside of $\{y_1, \dots, y_{k'}\}$ are less than any of $y_1, \dots, y_{k'}$. Therefore, we can name these elements in such a way that $(y_1, \dots, y_{k'}, y_{k'+1}, \dots, y_k)$ is a linear extension of $\{x_1, \dots, x_k\}$. Noting again that any two linear extensions of a poset differ by a sequence of swaps between adjacent incomparable elements [7], toggles of incomparable elements commute so $T_{x_1} T_{x_2} \cdots T_{x_k} = T_{y_1} \cdots T_{y_{k'}} T_{y_{k'+1}} \cdots T_{y_k}$.

From Eq. (4) and $\eta_{x_{k+1}} = T_{y_1} \cdots T_{y_{k'}}$, we obtain

$$\begin{aligned} \tau_{x_{k+1}}^* \tau_{x_k}^* \cdots \tau_{x_2}^* \tau_{x_1}^* &= \eta_{x_{k+1}} T_{x_{k+1}} \eta_{x_{k+1}}^{-1} T_{x_1} T_{x_2} \cdots T_{x_k} \\ &= T_{y_1} \cdots T_{y_{k'}} T_{x_{k+1}} E_{y_{k'}} \cdots E_{y_1} T_{y_1} \cdots T_{y_{k'}} T_{y_{k'+1}} \cdots T_{y_k} \\ &= T_{y_1} \cdots T_{y_{k'}} T_{x_{k+1}} T_{y_{k'+1}} \cdots T_{y_k} \\ &= T_{y_1} \cdots T_{y_{k'}} T_{y_{k'+1}} \cdots T_{y_k} T_{x_{k+1}} \\ &= T_{x_1} T_{x_2} \cdots T_{x_k} T_{x_{k+1}}. \end{aligned}$$

In the fourth equality above, we could move $T_{x_{k+1}}$ to the right of $T_{y_{k'+1}} \cdots T_{y_k}$ because x_{k+1} is incomparable with each of $y_{k'+1}, \dots, y_k$. This is because none of these are less than x_{k+1} by design nor greater than x_{k+1} by position within the linear extension (x_1, \dots, x_n) of P .

By induction, we have $\tau_{x_n}^* \cdots \tau_{x_2}^* \tau_{x_1}^* = T_{x_1} T_{x_2} \cdots T_{x_n} = \text{NOR} = \Theta \circ \Delta^{-1} \circ \nabla$ so

$$\tau_{x_n} \cdots \tau_{x_2} \tau_{x_1} = \text{NAR} = \nabla \circ \Theta \circ \Delta^{-1}. \quad \square$$

From Theorem 5.26, and the ensuing commutative diagrams, the orders of NAR and NOR are equal on any poset. So Grinberg’s Conjecture 5.10 is equivalent to the claim that NAR has order $a+b$ on $[a] \times [b]$. Although we do not resolve this conjecture here, we hope that giving another approach from the antichain perspective may be helpful in studying these questions.

Furthermore, it appears at every step of the process, the labels can be written in a way that is no more complicated than in the (commutative) birational realm. What we mean by that is they can be written in a way that contains every factor from the birational realm (multiplied in a certain order) and does *not* require extra factors that would cancel in the commutative realm. Compare Figures 3 and 5 for $P = [2] \times [3]$.

We can extend the main results on graded rescalings from § 4.2 to the noncommutative setting as long as each component of the rescaling vector (a_0, \dots, a_r) lies in the *center* of \mathbb{S} . Under this assumption Propositions 4.6 and 4.7 go through with BAR replaced by NAR. (The analogous results for NOR are true as well.) We omit the details.

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